Validation Report

Washington, SPS-2 Task Order 17, CLIN 2 November 28 to 29, 2006

1 Executive Summary	
2 Corrective Actions Recommended	3
3 Post Calibration Analysis	3
3.1 Temperature-based Analysis	6
3.2 Speed-based Analysis	9
3.3 Classification Validation	
3.4 Evaluation by ASTM E-1318 Criteria	
4 Pavement Discussion	
4.1 Profile Analysis	
4.2 Distress Survey and Any Applicable Photos	
4.3 Vehicle-pavement Interaction Discussion	
5 Equipment Discussion	
5.1 Pre-Evaluation Diagnostics	16
5.2 Calibration Process	16
5.2.1 Calibration Iteration 1	16
5.3 Summary of Traffic Sheet 16s	19
5.4 Projected Maintenance/Replacement Requirements	19
6 Pre-Validation Analysis	
6.1 Temperature-based Analysis	23
6.2 Speed-based Analysis	26
6.3 Classification Validation	28
6.4 Evaluation by ASTM E-1318 Criteria	29
6.5 Prior Validations	29
7 Data Availability and Quality	30
8 Data Sheets	34
9 Updated Handout Guide and Sheet 17	34
10 Updated Sheet 18	35
11 Traffic Sheet 16(s)	35

List of Tables

Table 1-1 Post-Validation results – 530200 – 29-Nov-2006	1
Table 1-2 Results Based on ASTM E-1318-02 Test Procedures	2
Table 3-1 Post-Validation Results - 530200 - 29-Nov-2006	3
Table 3-2 Post-Validation Results by Temperature Bin – 530200 – 29-Nov-2006	6
Table 3-3 Post-Validation Results by Speed Bin – 530200 – 29-Nov-2006	9
Table 3-4 Truck Misclassification Percentages for 530200 – 29-Nov-2006	12
Table 3-5 Truck Classification Mean Differences for 530200 – 29-Nov-2006	13
Table 3-6 Results of Validation Using ASTM E-1318-02 Criteria	13
Table 4-1 Thresholds for WIM Index Values	14
Table 4-2 WIM Index Values - 530200 -7-Jun-2006	15
Table 5-1 Pre-Validation Results – 530200 – 28-Nov-2006	18
Table 5-2 Calibration Iteration 1 Results - 530200 - 29-Nov-2006 (9:31:00 AM)	18
Table 5-3 Classification Validation History – 530200 – 29-Nov-2006	19
Table 5-4 Weight Validation History – 530200 – 29-Nov-2006	19
Table 6-1 Pre-Validation Results – 530200 – 28-Nov-2006	20
Table 6-2 Pre-Validation Results by Temperature Bin – 530200 – 28-Nov-2006	23
Table 6-3 Pre-Validation Results by Speed Bin – 530200 – 28-Nov-2006	26
Table 6-4 Truck Misclassification Percentages for 530200 – 28-Nov-2006	28
Table 6-5 Truck Classification Mean Differences for 530200 – 28-Nov-2006	29
Table 6-6 Results of Validation Using ASTM E-1318-02 Criteria	29
Table 7-1 Amount of Traffic Data Available 530200 – 28-Nov-2006	30
Table 7-2 GVW Characteristics of Major sub-groups of Trucks - 530200 - 29-Nov-	2006
	31

List of Figures

Figure 3-1 Post-Validation Speed-Temperature Distribution – 530200 – 29-Nov-2006 4
Figure 3-2 Post-validation GVW Percent Error vs. Speed – 530200 – 29-Nov-2006 5
Figure 3-3 Post-Validation GVW Percent Error vs. Temperature – 530200 – 29-Nov-
20065
Figure 3-4 Post-Validation Spacing vs. Speed – 530200 – 29-Nov-2006
Figure 3-5 Post-Validation GVW Percent Error vs. Temperature by Truck – 530200 – 29-
Nov-2006
Figure 3-6 Post-Validation Steering Axle Error vs. Temperature by Group – 530200 – 29-
Nov-2006
Figure 3-7 Post-Validation Tandem Axle Error vs. Temperature by Group – 530200 – 29-
Nov-2006
Figure 3-8 Post-Validation GVW Percent Error vs. Speed by Truck – 530200 – 29-Nov-
2006
Figure 3-9 Post-Validation Steering Axle Percent Error vs. Speed by Group – 530200 –
29-Nov-2006
Figure 3-10 Post-Validation Tandem Axle Percent Error by Truck and Speed – 530200 –
29-Nov-2006
Figure 5-1 Pre-validation GVW Percent Error vs. Speed – 530200 – 28-Nov-2006 17
Figure 5-2 Pre-Validation Steering Axle Percent Error vs. Speed Group - 530200 –28-
Nov-2006
Figure 5-3 Calibration I teration 1 GVW Percent Error vs. Speed Group – 530200 – 29-
Nov-2006 (9:31:00 AM)
Figure 6-1 Pre-Validation Speed-Temperature Distribution – 530200 – 28-Nov-2006 21
Figure 6-2 Pre-validation GVW Percent Error vs. Speed – 530200 – 28-Nov-2006 21
Figure 6-3 Pre-Validation GVW Percent Error vs. Temperature – 530200 – 28-Nov-2006
22 CAR WHILE G. I. 500000 20 N. 2006
Figure 6-4 Pre-Validation Spacing vs. Speed - 530200 – 28-Nov-2006
Figure 6-5 Pre-Validation GVW Percent Error vs. Temperature by Truck – 530200 – 28-
Nov-2006
Figure 6-6 Pre-Validation Steering Axle Error vs. Temperature by Group – 530200 – 28-
Nov-2006
Figure 6-7 Pre-Validation Tandem Axle Error vs. Temperature by Group – 530200 – 28-
Nov-2006
Figure 6-8 Pre-Validation GVW Percent Error vs. Speed Group - 530200 –28-Nov-2006
Figure 6-9 Pre-Validation Steering Axle Percent Error vs. Speed Group - 530200 –28-
Nov-2006
Figure 6-10 Pre-Validation Tandem Axle Percent Error by Truck and Speed – 530200 –
29-Nov-2006
Figure 7-1 Expected GVW Distribution Class 5 – 530200 – 29-Nov-2006
Figure 7-2 Expected GVW Distribution Class 9 – 530200 – 29-Nov-2006
Figure 7-3 Expected GVW Distribution Class 10 – 530200 – 29-Nov-2006
Figure 7-4 Expected Vehicle Distribution – 530200 – 29-Nov-2006
Figure 7-5 Expected Speed Distribution – 530200 – 29-Nov-2006

1 Executive Summary

A visit was made to the Washington 0200 on November 28 to 29, 2006 for the purposes of conducting a validation of the WIM system located on I-395, located 2 miles south of I-90, near Ritzville, Washington. The SPS-2 is located in the righthand, northbound lane of a four-lane divided facility. It is designated as lane number 1 by the controller. All lanes at this site are instrumented for WIM. The LTPP lane and the adjacent lane are instrumented with quartz sensors. The two lanes in the opposite direction are instrumented with piezo sensors. The validation procedures were in accordance with LTPP's SPS WIM Data Collection Guide dated August 21, 2001.

This is the first validation visit to this location. The site was installed on March, 1998 by the Washington DOT. An LTPP Assessment was performed on May 24, 2006.

This site meets LTPP precision requirements for loading data. The classification algorithm does not provide research quality classification information.

The site is instrumented with quartz piezo WIM sensors and IRD 1068 electronics. It is installed in portland cement concrete, 400 feet long.

The validation used the following trucks:

- 1) 5-axle tractor-trailer with a tractor having an air suspension and trailer with a standard rear tandem and air suspension loaded to 75,840 lbs., the "golden" truck.
- 2) 5-axle tractor semi-trailer with a tractor having an air suspension and a trailer with a standard rear tandem and tapered leaf suspension loaded to 67,720 lbs., the "partial" truck.

The validation speeds ranged from 46 to 60 miles per hour. The pavement temperatures ranged from 16 to 27 degrees Fahrenheit. The desired speed range was achieved during this validation. The desired 30 degree Fahrenheit temperature range was not achieved.

Table 1-1 Post-Validation results – 530200 – 29-Nov-2006

SPS-1, -2, -5, -6 and -8	95 %Confidence	Site Values	Pass/Fail
	Limit of Error		
Steering axles	±20 percent	$-3.7 \pm 11.5\%$	Pass
Tandem axles	±15 percent	$1.2 \pm 8.4\%$	Pass
GVW	±10 percent	$0.3 \pm 6.4\%$	Pass
Speed	<u>+</u> 1 mph [2 km/hr]	N/A	N/A
Axle spacing	<u>+</u> 0.5 ft [150mm]	$0.0 \pm 0.1 \text{ ft}$	Pass

The pavement condition was satisfactory for conducting a performance evaluation. There were no distresses observed that would influence truck motions significantly. A visual survey determined that there is no discernable bouncing; however, a moderate number of trucks appeared to track down the right side of the travel lane although they did not appear to avoid the WIM sensors.

If this site had been evaluated using ASTM E-1318-02 it would have met the conditions for a Type I site exclusive of wheel loads. LTPP does not validate WIM performance with respect to wheel loads.

Table 1-2 Results Based on ASTM E-1318-02 Test Procedures

	Limits for Allowable	Percent within	
Characteristic	Error	Allowable Error	Pass/Fail
Single Axles	± 20%	100%	Pass
Axle Groups	± 15%	100%	Pass
GVW	± 10%	100%	Pass

This site needs 5 years of data to meet the goal of five years of research quality data.

2 Corrective Actions Recommended

The classification algorithm at this site needs to be changed to allow for the proper classification of several truck types with atypical axle spacings and lighter axle weights than is allowed by the installed algorithm. No other corrective actions are required at this site at this time.

3 Post Calibration Analysis

This final analysis is based on test runs conducted November 29, 2006 during the mid morning to early evening hours at test site 530200 on I-395. This SPS-2 site is at milepost 93 on the northbound, righthand of a four-lane divided facility. No auto-calibration was used during test runs. The two trucks used for the calibration and for the subsequent validation included:

- 1. 5-axle tractor-trailer with a tractor having an air suspension and trailer with a standard rear tandem and air suspension loaded to 75,840 lbs., the "golden" truck.
- 2. 5-axle tractor semi-trailer with a tractor having an air suspension and a trailer with a standard rear tandem and tapered leaf suspension loaded to 67,720 lbs., the "partial" truck.

Each truck made a total of 20 passes over the WIM scale at speeds ranging from approximately 46 to 60 miles per hour. The desired speed range was achieved during this validation. Pavement surface temperatures were recorded during the test runs ranging from about 16 to 27 degrees Fahrenheit. The desired 30 degree Fahrenheit temperature range was not achieved. The computed values of 95% confidence limits of each statistic for the total population are in Table 3-1.

As shown in Table 3-1, this site passed all of the performance criteria for weight and spacing. Speed testing during post-validation was not performed since the speed error during pre-validation testing was 0.1 mph.

Table 3-1 Post-Validation Results - 530200 - 29-Nov-2006

SPS-1, -2, -5, -6 and -8	95 %Confidence Limit of Error	Site Values	Pass/Fail
Steering axles	+20 percent	$-3.7 \pm 11.5\%$	Pass
Tandem axles	±15 percent	$1.2 \pm 8.4\%$	Pass
GVW	±10 percent	$0.3 \pm 6.4\%$	Pass
Speed	<u>+</u> 1 mph [2 km/hr]	N/A	N/A
Axle spacing	<u>+</u> 0.5 ft [150mm]	$0.0 \pm 0.1 \text{ ft}$	Pass

The test runs were conducted primarily during the mid-morning to early evening hours, resulting in a narrow range of pavement temperatures. The runs were also conducted at various speeds to determine the effects of these variables on the performance of the WIM scale. To investigate these effects, the dataset was split into three speed groups and left

as one temperature group. The distribution of runs by speed and temperature is illustrated in Figure 3-1. The figure indicates that the desired distribution of speed and temperature combinations was not achieved for this set of validation runs. Temperatures at this site during testing hours remained very low, without much increase throughout the day.

The three speed groups were divided as follows: Low speed -46 to 51 mph, Medium speed -52 to 58 mph and High speed -59 + mph. The one temperature group was labeled the medium temperature range, with a range from 16 to 27 degrees Fahrenheit.

Speed versus Temperature Combinations

65 63 61 59 55 51 49 47 45 10 15 20 25 30 35 40 Temperature (F)

Figure 3-1 Post-Validation Speed-Temperature Distribution – 530200 – 29-Nov-2006

A series of graphs was developed to investigate visually any sign of a relationship between speed or temperature and the scale performance. Figure 3-2 shows the GVW Percent Error vs. Speed graph for the population as a whole.

Figure 3-2 shows the GVW Percent Error vs. Speed graph for the population as a whole. From the figure, it appears that the equipment estimates GVW fairly accurately and consistently throughout the entire speed range. Variability in error appears to be lesser at medium speeds when compared with low and high speeds.



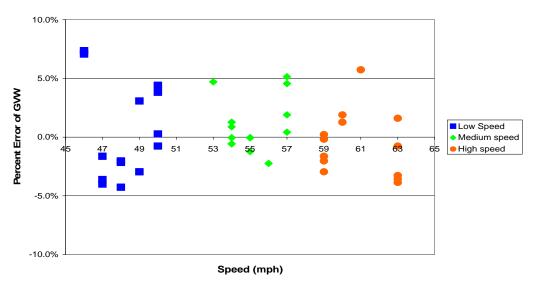


Figure 3-2 Post-validation GVW Percent Error vs. Speed – 530200 – 29-Nov-2006

Figure 3-3 shows a lack of a relationship between temperature and GVW percentage error, although the GVW estimation appears to decrease slightly as the temperature increases.

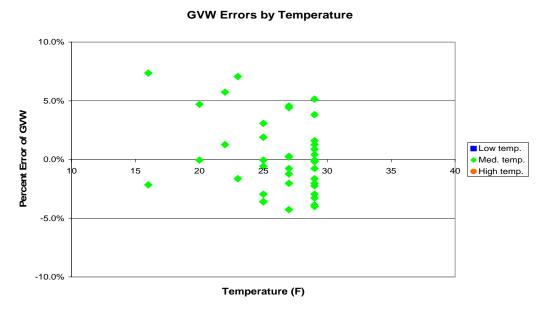


Figure 3-3 Post-Validation GVW Percent Error vs. Temperature – 530200 - 29-Nov-2006

Figure 3-4 shows the relationship between the drive tandem spacing errors in feet and speeds. This graph is used as a potential indicator of classification errors due to failure to

correctly identify spacings on a vehicle. Since the most common reference value is the drive tandem on a Class 9 vehicle, this is the spacing evaluated and plotted for validations. The graph indicates that the errors in tandem spacings for the test trucks were not affected by changes in speed.

Figure 3-4 Post-Validation Spacing vs. Speed – 530200 – 29-Nov-2006

3.1 Temperature-based Analysis

The one temperature groups were created by defining all of the test runs as the Medium temperature range, from 16 to 27 degrees Fahrenheit.

Table 3-2 Post-Validation Results by Temperature Bin – 530200 – 29-Nov-2006

Element	95%	Medium
	Limit	Temperature 16-27 °F
Steering axles	<u>+</u> 20 %	$-3.7 \pm 11.5\%$
Tandem axles	<u>+</u> 15 %	$1.2 \pm 8.4\%$
GVW	<u>+</u> 10 %	$0.3 \pm 6.4\%$
Speed	<u>+</u> 1 mph	N/A
Axle spacing	<u>+</u> 0.5 ft	$0.0 \pm 0.1 \text{ ft}$

From Table 3-2, it appears that the equipment underestimates steering axle weights, and generally overestimates tandem and GVW weights. The variability in steering axles also appears to be greater than that of tandem and GVW errors.

Figure 3-5 is the distribution of GVW Errors versus Temperature by Truck graph. From the figure, it appears that mean error for the Golden truck (squares) was not particularly affected by temperature; however, GVW estimation for the Partial truck (diamonds) appears to go from an overestimation at the lower end of the range, to fairly accurate estimation at the upper end of the range.

GVW Errors vs. Temperature by Truck

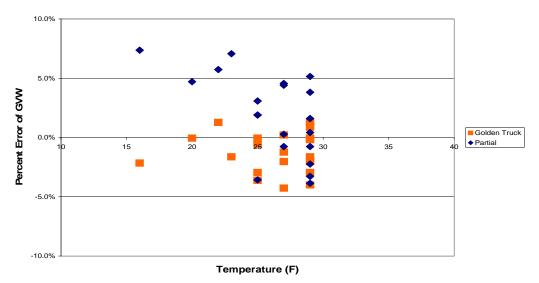


Figure 3-5 Post-Validation GVW Percent Error vs. Temperature by Truck – 530200 – 29-Nov-2006

Figure 3-6 shows the relationship between steering axle errors and temperature. This graph is included due to the frequent use of steering axle weights of Class 9 vehicles for calibration. This site does not use auto-calibration. The steering axles in this graph are associated only with Class 9 vehicles.

From the figure, it can be seen that the estimation of Steering axle weights transitions from an overestimation at the lower end of the range to an underestimation at the higher end.

Steering Axle Errors vs. Temperature

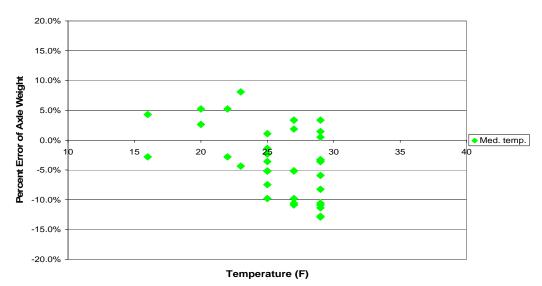


Figure 3-6 Post-Validation Steering Axle Error vs. Temperature by Group – 530200 – 29-Nov-2006

Figure 3-7 shows the relation between tandem axle errors and temperature. From the figure, it appears that temperature has no effect on tandem axle weight estimation for the Golden truck, however, the estimation of tandem axle weights for the Partial truck appear to decrease as temperature increases much like the GVW estimation for this truck.

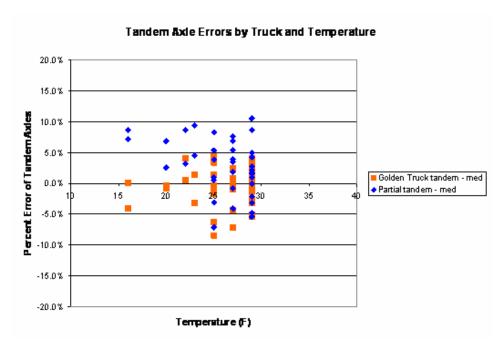


Figure 3-7 Post-Validation Tandem Axle Error vs. Temperature by Group -530200 -29-Nov-2006

3.2 Speed-based Analysis

The three speed groups were divided using 46 to 51 mph for Low speed, 52 to 58 mph for Medium speed and 59+ mph for High speed.

Table 3-3 Post-Validation Results by Speed Bin – 530200 – 29-Nov-2006

Element	95% Limit	Low Speed 46 to 51 mph	Medium Speed 52 to 58 mph	High Speed 59+ mph
Steering axles	<u>+</u> 20 %	$-3.4 \pm 12.0\%$	$-2.5 \pm 12.8\%$	$-5.1 \pm 12.5\%$
Tandem axles	<u>+</u> 15 %	$1.1 \pm 9.5\%$	$1.9 \pm 7.2\%$	$0.5 \pm 9.1\%$
GVW	<u>+</u> 10 %	$0.3 \pm 8.8\%$	$1.1 \pm 5.1\%$	$-0.6 \pm 6.0\%$
Speed	<u>+</u> 1 mph	N/A	N/A	N/A
Axle spacing	<u>+</u> 0.5 ft	0.0 ± 0.1 ft	$0.0 \pm 0.1 \text{ ft}$	$0.0 \pm 0.1 \text{ ft}$

From Table 3-3, it can be seen that the equipment tends to estimate all weights fairly consistently throughout the entire speed range. Steering axle weights appear to be underestimated at all speeds, with greater underestimation at the higher speeds. Variability in steering axle weight appears to be consistent throughout the entire speed range, while the spread in error for GVW and tandem weights appears to be lesser at the medium speeds when compared with the spread at low and high speeds.

Figure 3-8 illustrates the tendency for the system to overestimate GVW at all speeds for the population as a whole. However, it appears that the equipment overestimates GVW for the Partial truck while generally underestimating GVW for the Golden truck over the entire range of speeds. The variability of error for the population as a whole as well as for each truck appears to be fairly consistent throughout the entire speed range, although the spread in error for the Partial truck appears greater than the error spread for the Golden truck.

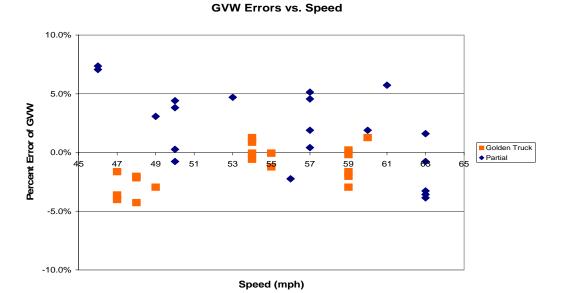


Figure 3-8 Post-Validation GVW Percent Error vs. Speed by Truck-530200-29-Nov-2006

Figure 3-9 shows the relationship between steering axle errors and speed. This graph is included due to the frequent use of steering axle weights of Class 9 vehicles for autocalibration. This site does not use auto-calibration. The steering axles in this graph are associated only with Class 9 vehicles.

From the figure, it appears that the WIM equipment underestimates steering axle weights fairly consistently at all speeds.

Steering Axle Errors vs. Speed

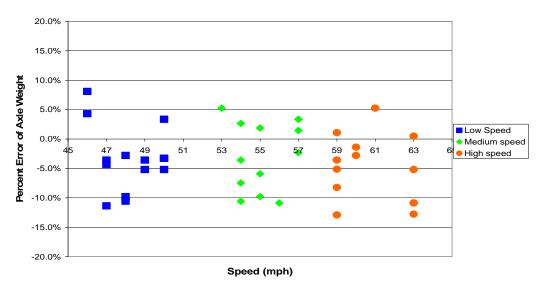


Figure 3-9 Post-Validation Steering Axle Percent Error vs. Speed by Group – 530200 – 29-Nov-2006

Figure 3-10 shows the differing tandem axle errors by truck over the speed range. From the figure, it can be seen that the equipment generally estimates the tandem axle weights accurately and consistently at the medium and high speeds for both trucks. At low speeds, it appears that the equipment overestimates the tandem axle weights of the Partial truck while underestimating the tandem axle weights of the Golden truck. The variability in error appears to be greater for the Partial truck at all speeds.

Tandem Axle Errors by Truck and Speed

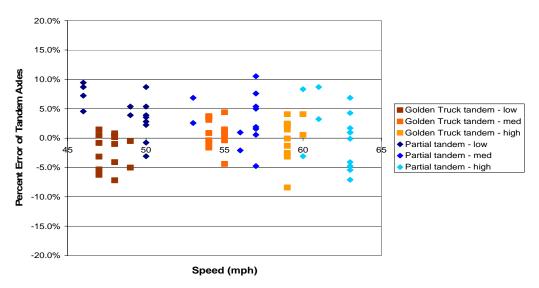


Figure 3-10 Post-Validation Tandem Axle Percent Error by Truck and Speed – 530200 – 29-Nov-2006

3.3 Classification Validation

This site uses the FHWA 13-bin classification scheme and the LTPP classification algorithm, mod 3. Classification 15 has been added to account for unclassified vehicles.

The classification validation is intended to find gross errors in vehicle classification, not to validate the installed algorithm. A sample of 100 trucks was collected at the site. Video was taken at the site to provide ground truth for the evaluation. Based on a 100 percent sample it was determined that there are 0 percent unknown vehicles and 1 percent unclassified vehicles. The unclassified vehicle was a 6 axle, multiple tractor-trailer combination truck with a standard rear tandem on the second trailer.

The second check is the ability of the algorithm to correctly distinguish between truck classes with no more than 2% errors in such classifications. Table 3-4 has the classification error rates by class. The overall misclassification rate is 1. percent.

Table 3-4 Truck Misclassification Percentages for 530200 – 29-Nov-2006

Class	Percent Error	Class	Percent Error	Class	Percent Error
4	N/A	5	0	6	0
7	N/A				
8	50	9	0	10	0
11	N/A	12	0	13	0

The misclassification percentage is computed as the probability that a pair containing the class of interest does NOT include a match. Thus if there are eight pairs of observations with at least one Class 9 and only six of them are matches, the error rate is 25 percent.

The percent error and the mean differences reported below do not represent the same statistic. It is possible to have error rates greater than 0 with a mean difference of zero.

Table 3-5 Truck Classification Mean Differences for 530200 – 29-Nov-2006

Class	Mean Difference	Class	Mean Difference	Class	Mean Difference
4	N/A	5	0	6	0
7	N/A				
8	-50	9	0	10	0
11	N/A	12	0	13	0

These error rates are normalized to represent how many vehicles of the class are expected to be over or under-counted for every hundred of that class observed by the equipment. Thus a value of 0 means the class is identified correctly on average. A number between -1 and -100 indicates at least that number of vehicles either missed or not assigned to the class by the equipment. It is not possible to miss more than all of them or one hundred out of one hundred. Numbers 1 or larger indicate at least how many more vehicles are assigned to the class than the actual "hundred observed". Classes marked Unknown are those identified by the equipment but no vehicles of the type were seen by the observer. There is no way to tell how many vehicles of that type might actually exist. N/A means no vehicles of the class were recorded by either the equipment or the observer. The large mean error rates for Class 8s in Table 3-5 reflect the small number of Class 8 vehicles (2 sampled), one of which was classified as a type 15 due to a shorter 1 axle 1 to 2 spacing (10.6') than is allowed by the classification algorithm (11.0').

3.4 Evaluation by ASTM E-1318 Criteria

The ASTM E-1318 criteria for a successful validation of Type I sites is 95% of the observed errors within the limits for allowable errors for each of the relevant statistics. If this site had been evaluated using ASTM E-1318-02 it would have met the conditions for a Type I site exclusive of wheel loads. LTPP does not validate WIM performance with respect to wheel loads.

Table 3-6 Results of Validation Using ASTM E-1318-02 Criteria

	Limits for Allowable	Percent within	
Characteristic	Error	Allowable Error	Pass/Fail
Single Axles	$\pm 20\%$	100%	Pass
Axle Groups	± 15%	100%	Pass
GVW	± 10%	100%	Pass

4 Pavement Discussion

The pavement condition did not appear to influence truck movement across the sensors.

4.1 Profile Analysis

The WIM site is a section of pavement that is 305 meters long with the WIM scale located at 274.5 meters from the beginning of the test section. An ICC profiler was used

to collect longitudinal profiles of the test section with a sampling interval of 25 millimeters.

Profile data collected at the SPS WIM location by Nichols Consulting Engineers on June 7, 2006 were processed through the LTPP SPS WIM Index software, version 1.1. This WIM scale is installed on a rigid pavement.

A total of 8 profiler passes were conducted over the WIM site. Since the issuance of the LTPP directive on collection of longitudinal profile data for SPS WIM sections, the requirements have been a minimum of 3 passes in the center of the lane and one shifted to each side. For this site the RSC has completed 4 passes at the center of the lane, 2 passes shifted to the left side of the lane, and 2 passes shifted to the right side of the lane. Shifts to the sides of the lanes were made such that data were collected as close to the lane edges as was safely possible. For each profiler pass, profiles were recorded under the left wheel path (LWP) and the right wheel path (RWP).

The SPS WIM Index software was developed with four different indices: LRI, SRI, Peak LRI and Peak SRI. The LRI incorporates the pavement profile starting 25.8 m prior to the scale and ending 3.2 m after the scale in the direction of travel. The SRI incorporates a shorter section of pavement profile beginning 2.74 m prior to the WIM scale and ending 0.46 m after the scale. The LRI and SRI are the index values for the actual location of the WIM scale. Peak LRI is the highest value of LRI, within 30 m prior to the scale. Peak SRI indicates the highest value of SRI that is located between 2.45 m prior to the scale and 1.5 m after the scale. Also, a range for each of the indices was developed to provide the smoothness criteria. The ranges are shown in Table 4-1. When all of the values are below the lower thresholds, it is presumed unlikely that pavement smoothness will significantly influence sensor output. When one or more values exceed an upper threshold there is a reasonable expectation that the pavement smoothness will influence the outcome of the validation. When all values are below the upper threshold but not all below the lower threshold, the pavement smoothness may or may not influence the validation outcome.

Table 4-1 Thresholds for WIM Index Values

Index	Lower Threshold (m/km)	Upper Threshold (m/km)
LRI	0.50	2.1
SRI	0.50	2.1
Peak LRI	0.50	2.1
Peak SRI	0.75	2.9

Table 4-2 shows the computed index values for all 8 profiler passes for this WIM site. The average values over the passes in each path were also calculated when three or more passes were completed. These are shown in the right most column of the table. Values above the upper index limits are presented in bold while values below the lower index limits are presented in italics.

Table 4-2 WIM Index Values - 530200 -7-Jun-2006

Profiler	Profiler Passes		Pass 1	Pass 2	Pass 3	Pass 4	Pass 5	Ave.
		LRI (m/km)	1.139	1.181	1.151	1.130		1.150
	LWP	SRI (m/km)	0.616	0.888	0.715	0.853		0.768
	LWF	Peak LRI (m/km)	1.303	1.275	1.279	1.211		1.267
Center		Peak SRI (m/km)	1.110	1.202	0.910	1.041		1.066
Center		LRI (m/km)	1.185	1.172	1.249	1.201		1.202
	RWP	SRI (m/km)	1.409	1.385	1.403	1.659		1.464
	KWF	Peak LRI (m/km)	1.206	1.225	1.270	1.258		1.240
		Peak SRI (m/km)	1.410	1.457	1.466	1.671		1.501
		LRI (m/km)	1.076	0.865				
	LWP	SRI (m/km)	1.049	1.074				
	LWF	Peak LRI (m/km)	1.108	1.011				
Left		Peak SRI (m/km)	1.213	1.262				
Shift	RWP	LRI (m/km)	0.913	1.063				
		SRI (m/km)	0.972	1.408				
		Peak LRI (m/km)	0.962	1.075				
		Peak SRI (m/km)	1.251	1.725				
		LRI (m/km)	0.956	0.850				
	LWP	SRI (m/km)	1.032	0.606				
	LWF	Peak LRI (m/km)	1.062	0.929				
Right		Peak SRI (m/km)	1.250	0.796				
Shift		LRI (m/km)	2.109	1.183				
	RWP	SRI (m/km)	1.490	1.707				
	KWP	Peak LRI (m/km)	2.175	1.231				
		Peak SRI (m/km)	2.318	1.762				

From Table 4-2 it can be seen that 2 values are above the upper threshold values indicating that it is likely that the pavement roughness could interfere with ability to calibrate this scale.

4.2 Distress Survey and Any Applicable Photos

During a visual survey of the pavement no distresses that would influence truck movement across the WIM scales were noted.

4.3 Vehicle-pavement Interaction Discussion

A visual observation of the trucks as they approach, traverse and leave the sensor area did not indicate any visible motion of the trucks that would affect the performance of the WIM scales. A moderate number of trucks appeared to track down the right side of the lane, none of which appeared to avoid the WIM sensors. Daylight cannot be seen between the tires of any of the sensors for the equipment.

5 Equipment Discussion

The traffic monitoring equipment at this location includes quartz piezo and IRD 1068 electronics. These sensors are installed in a portland cement concrete pavement.

There were no changes in basic equipment operating condition since the assessment on May 24, 2006.

5.1 Pre-Evaluation Diagnostics

A complete electronic and electrical check of all system components including in-road sensors, electrical power, and telephone service were performed immediately prior to the evaluation. All sensors and system components were found to be within operating parameters.

5.2 Calibration Process

The equipment required one-iteration of the calibration process between the initial 40 runs and the final 40 runs.

5.2.1 Calibration Iteration 1

For this equipment, there are 3 speed designated weight compensation factors that affect all weight estimations by the equipment and 1 dynamic factor that affects only the steering axle weight estimation. All factors are adjusted to directly affect the weight reported by the WIM equipment. To reduce overestimation of weights these factors are reduced by the same percentage of the overestimation. If the weights are underestimated, these factors are increased by the same percentage as the mean error.

For this equipment, the original compensation factors were:

- 80 kph 6.500298
- 100 kph 6.500298
- 120 kph 6.500298

The results of the Pre-Validation from November 28, 2006 are illustrated in Figure 5-1 and Figure 5-2, and Table 5-1. As shown, the equipment demonstrated a tendency to underestimate GVW and Steering axle weights at all speeds. Scatter appeared to be fairly consistent at all speeds, with only a few outliers.

GVW Errors by Speed Group

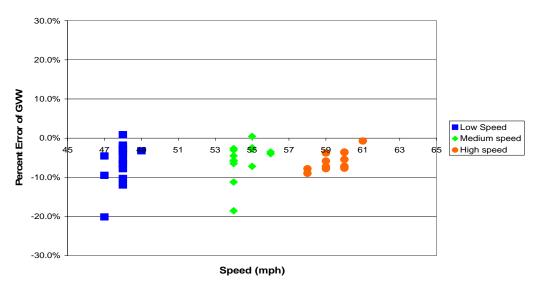


Figure 5-1 Pre-validation GVW Percent Error vs. Speed – 530200 – 28-Nov-2006



Figure 5-2 Pre-Validation Steering Axle Percent Error vs. Speed Group - 530200 – 28-Nov-2006

Table 5-1 Pre-Validation Results – 530200 – 28-Nov-2006

SPS-1, -2, -5, -6 and -8	95 %Confidence	Site Values	Pass/Fail
	Limit of Error		
Steering axles	<u>+</u> 20 percent	$-12.9 \pm 7.3\%$	Fail
Tandem axles	<u>+</u> 15 percent	-4.5 ± 11.7%	Fail
GVW	<u>+</u> 10 percent	$-6.0 \pm 8.6\%$	Fail
Speed	<u>+</u> 1 mph [2 km/hr]	$0.0 \pm 1.3 \text{ mph}$	Fail
Axle spacing	<u>+</u> 0.5 ft [150mm]	$0.0 \pm 0.1 \text{ ft}$	Pass

Table 5-1 illustrates the tendency to underestimate GVW by 6% and steering axle weights by 12.9%. As a result, the dynamic factor was increased by 8.4%, from 91 to 99 and all speed factors were increased by 3 percent, from 6.500298 to 6.6 90134. Changes were made by the state representative.

Table 5-2 and Figure 5-3 illustrate the results of the first iteration.

Table 5-2 Calibration Iteration 1 Results – 530200 – 29-Nov-2006 (9:31:00 AM)

SPS-1, -2, -5, -6 and -8	95 %Confidence Limit of Error	Site Values	Pass/Fail
Steering axles	±20 percent	-2.3 ± 12.4%	Pass
Tandem axles	±15 percent	$2.1 \pm 8.9\%$	Pass
GVW	±10 percent	$1.3 \pm 7.6\%$	Pass
Speed	<u>+</u> 1 mph	N/A	N/A
Axle spacing	<u>+</u> 0.5 ft	$0.0 \pm 0.1 \text{ ft}$	Pass

GVW Errors by Speed Group

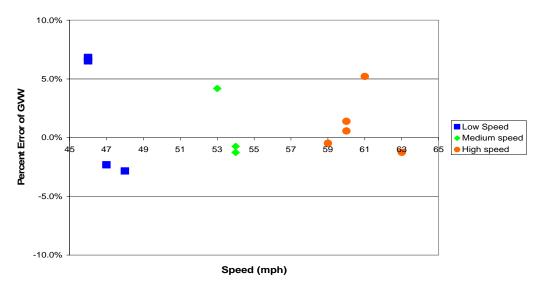


Figure 5-3 Calibration Iteration 1 GVW Percent Error vs. Speed Group – 530200 – 29-Nov-2006 (9:31:00 AM)

5.3 Summary of Traffic Sheet 16s

This site has validation information from previous visits as well as the current one in the tables below. Table 5-3 has the information that would be found in

TRF_CALIBRATION_AVC for Sheet 16s submitted prior to this validation as well as the information for the current visit.

Table 5-3 Classification Validation History – 530200 – 29-Nov-2006

Date	Method		Percent			
		Class 9	Class 8	Class 10	Other 2	Unclassified
29-Nov-06	Manual	0	-50			1.0
28-Nov-06	Manual	0	-50			1.0
24-May-06	Manual	-2		-17		0.7

Table 5-4 has the information to be found in TRF_CALIBRATION_WIM for Sheet 16s for the current visit as well as information from other site validation activities.

Table 5-4 Weight Validation History – 530200 – 29-Nov-2006

Date	Method	Mean Error and (SD)				
		GVW	Single Axles	Tandem Axles		
29-Nov-06	Test Trucks	0.3 (3.2)	-3.7 (5.7)	1.2 (4.2)		
28-Nov-06	Test Trucks	-6 (4.2)	-12.9 (3.6)	-4.5 (5.9)		
18-Jan-06	Test Trucks	-3.6 (1.6)	3.1 (2.4)	-4.9 (2.4)		
06-May-04	Test Trucks	1.9 (1.4)	-1.3 (7.4)	2.5 (1.1)		

5.4 Projected Maintenance/Replacement Requirements

The classification algorithm at this site should be reviewed and corrected to remedy classification errors with Class 8 vehicles noted previously. There are no other corrective maintenance actions required at this site at this time.

6 Pre-Validation Analysis

This pre-validation analysis is based on test runs conducted November 28, 2006 during the mid-morning to early afternoon hours at 530200 on 2 miles south of I-90. This SPS-2 site is at milepost 93 on I-395 in the northbound, righthand of a four-lane divided facility. No auto-calibration was used during test runs. The two trucks used for initial validation included:

1. 5-axle tractor semi-trailer combination with a tractor having an air suspension and trailer with standard rear tandem and an air suspension loaded to 76,370 lbs.

2. 5-axle tractor semi-trailer with a tractor having an air suspension and a trailer with standard rear tandem and tapered leaf suspension loaded to 68,010 lbs., the partial truck.

For the initial validation each truck made a total of 20 passes over the WIM scale at speeds ranging from approximately 47 to 60 miles per hour. The desired speed range was achieved during this validation. Pavement surface temperatures were recorded during the test runs ranging from about 14 to 23 degrees Fahrenheit. The desired 30 degree Fahrenheit temperature range was not achieved. The computed values of 95% confidence limits of each statistic for the total population are in Table 6-1.

As shown in Table 6-1, the site failed all of the performance criteria for weight. As a result, it was determined that a calibration of the system was necessary.

Table 6-1 Pre-Validation Results - 530200 - 28-Nov-2006

SPS-1, -2, -5, -6 and -8	95 %Confidence	Site Values	Pass/Fail
	Limit of Error		
Steering axles	<u>+</u> 20 percent	$-12.9 \pm 7.3\%$	Fail
Tandem axles	+15 percent	-4.5 ± 11.7%	Fail
GVW	±10 percent	$-6.0 \pm 8.6\%$	Fail
Speed	<u>+</u> 1 mph [2 km/hr]	$0.0 \pm 1.3 \text{ mph}$	Fail
Axle spacing	+ 0.5 ft [150mm]	0.0 ± 0.1 ft	Pass

The test runs were conducted primarily during the mid-morning to early evening hours, resulting in a narrow range of pavement temperatures. The runs were also conducted at various speeds to determine the effects of these variables on the performance of the WIM scale. To investigate these effects, the dataset was split into three speed groups and evaluated as one temperature group. The distribution of runs within these groupings is illustrated in Figure 6-1. The figure indicates that the desired distribution of speed and temperature combinations was not achieved for this set of validation runs. Temperatures at this site during testing hours remained very low, without much increase throughout the day.

The three speed groups were divided into 47 to 51 mph for Low speed, 52 to 58 mph for Medium speed and 59+ mph for High speed. The one temperature group was created by leaving all of the test runs in one, Medium temperature group from 14 to 23 degrees Fahrenheit.

Speed versus Temperature Combinations

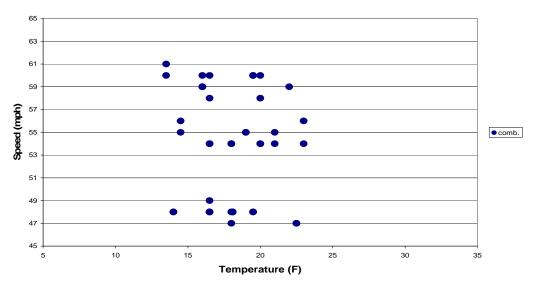


Figure 6-1 Pre-Validation Speed-Temperature Distribution – 530200 – 28-Nov-2006

A series of graphs was developed to investigate visually for any sign of any relationship between speed or temperature and the scale performance.

Figure 6-2 shows the GVW Percent Error vs. Speed graph for the population as a whole. The figure illustrates the tendency for the equipment to underestimate GVW at all speeds. Variability appears to remain fairly consistent over the entire speed range with the exception of a few outliers.

GVW Errors by Speed Group 30.0% 20.0% Percent Error of GVW 10.0% Low Speed 0.0% Medium speed 51 61 High speed 53 -10.0% -20.0% -30.0% Speed (mph)

Figure 6-2 Pre-validation GVW Percent Error vs. Speed - 530200 - 28-Nov-2006

Figure 6-3 shows the lack of relationship between temperature and GVW percentage error.

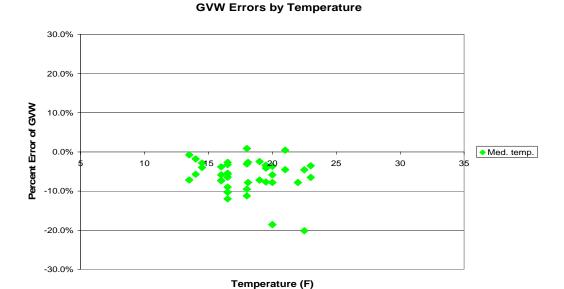


Figure 6-3 Pre-Validation GVW Percent Error vs. Temperature – 530200 – 28-Nov-2006

Figure 6-4 shows the relationship between the drive tandem spacing errors in feet and speeds. This graph is used as a potential indicator of classification errors due to failure to correctly identify spacings on a vehicle. Since the most common reference value is the drive tandem on a Class 9 vehicle, this is the spacing evaluated and plotted for validations. The graph indicates that the errors in tandem spacings for the test trucks were not affected by changes in speed.

Drive Tandem Spacing vs. Radar Speed

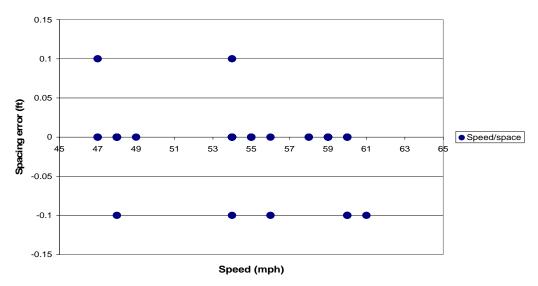


Figure 6-4 Pre-Validation Spacing vs. Speed - 530200 - 28-Nov-2006

6.1 Temperature-based Analysis

The one temperature group was created by combining all of the test runs into one Medium temperature group, from 14 to 23 degrees Fahrenheit.

Table 6-2 Pre-Validation Results by Temperature Bin – 530200 – 28-Nov-2006

Element	95% Limit	Medium Temperature 14-23 °F
Steering axles	<u>+</u> 20 %	-12.9 ± 7.3%
Tandem axles	<u>+</u> 15 %	-4.5 ± 11.7%
GVW	<u>+</u> 10 %	$-6.0 \pm 8.6\%$
Speed	<u>+</u> 1 mph	$0.0 \pm 1.3 \text{ mph}$
Axle spacing	<u>+</u> 0.5 ft	$0.0 \pm 0.1 \text{ ft}$

From Table 6-2, it appears that the equipment underestimates all weights. The variability in tandem axle errors appears to be greater than that of GVW and steering axle errors.

Figure 6-5 shows the distribution of GVW Errors versus Temperature by Truck. The equipment appears to underestimate all weights at all temperatures for the population as a whole. The underestimation for the Golden truck (squares) appears to be greater than the underestimation of the Partial truck (diamonds). The variability in error for the Golden truck appears to increase as the temperature increases. The variability in error for the Partial truck appears to remain constant over the entire range and it appears that the variability is lesser when compared with the Golden truck.

GVW Errors vs. Temperature by Truck

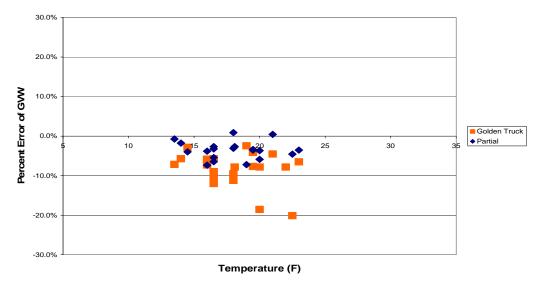


Figure 6-5 Pre-Validation GVW Percent Error vs. Temperature by Truck – 530200 – 28-Nov-2006

Figure 6-6 shows the relation between steering axle errors and temperature. This graph is included due to the frequent use of steering axle weights of Class 9 vehicles for autocalibration. This site does not use auto-calibration. The steering axles in this graph are associated only with Class 9 vehicles.

The figure shows that steering axle weights are consistently underestimated by the equipment over the temperature range.

Steering Axle Errors vs. Temperature

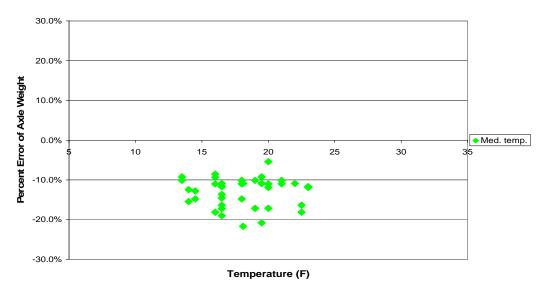


Figure 6-6 Pre-Validation Steering Axle Error vs. Temperature by Group – 530200 – 28-Nov-2006

Figure 6-7 shows the relation between tandem axle errors and temperature. From the figure, it appears that temperature has no effect on tandem axle weight estimation for the Partial truck. The underestimation of tandem axle weights for the Golden truck appears to increase as temperature increases within this range much like the GVW estimation for this truck.

Tandem Axle Errors by Truck and Temperature

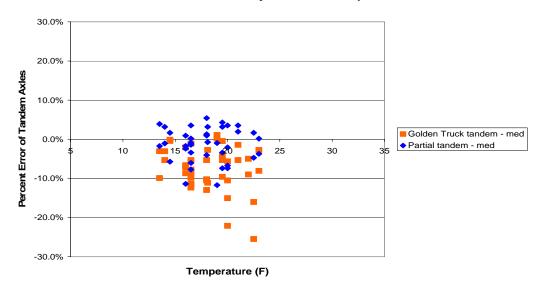


Figure 6-7 Pre-Validation Tandem Axle Error vs. Temperature by Group – 530200 – 28-Nov-2006

6.2 Speed-based Analysis

The speed groups were divided as follows: Low speed -47 to 51 mph, Medium speed -52 to 58 mph and High speed -59+ mph.

Table 6-3 Pre-Validation Results by Speed Bin – 530200 – 28-Nov-2006

Element 95% Limit		Low Speed 47 to 51 mph	Medium Speed 52 to 58 mph	High Speed 59+ mph	
Steering axles	<u>+</u> 20 %	$-14.8 \pm 8.7\%$	$-12.8 \pm 5.2\%$	$-11.0 \pm 7.4\%$	
Tandem axles	<u>+</u> 15 %	$-4.7 \pm 14.3\%$	$-3.9 \pm 12.2\%$	$-4.8 \pm 9.5\%$	
GVW	<u>+</u> 10 %	-6.5 ± 11.4%	$-5.6 \pm 10\%$	$-5.9 \pm 5.2\%$	
Speed	<u>+</u> 1 mph	$-0.2 \pm 1.3 \text{ mph}$	$-0.1 \pm 1.2 \text{ mph}$	$0.4 \pm 1.4 \text{ mph}$	
Axle spacing	<u>+</u> 0.5 ft	$0.0 \pm 0.1 \text{ ft}$	$0.0 \pm 0.1 \text{ ft}$	$0.0 \pm 0.1 \text{ ft}$	

From Table 6-3, it can be seen that the underestimation of steering axle weights appears to decrease as the speed increases. For tandem weights and GVW, the underestimation appears to remain fairly consistent over the entire speed range. Variability in errors for all weights appears to be greatest at low speeds. GVW error spread decreases dramatically at the higher speeds, while tandem axle error spread appears to decrease at a lesser rate as speed increases.

Figure 6-8 illustrates the tendency of the equipment to underestimate GVW for both trucks at all speeds. The underestimation and variability in error appear to be greater for the Golden truck when compared with the Partial truck.

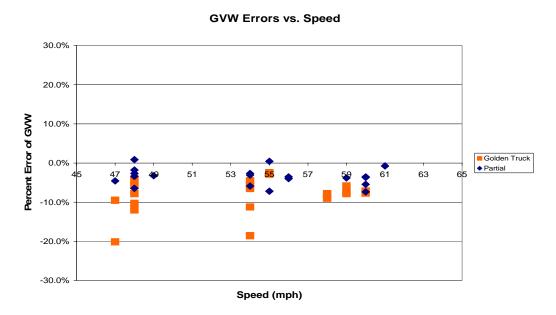


Figure 6-8 Pre-Validation GVW Percent Error vs. Speed Group - 530200 –28-Nov-2006

Figure 6-9 shows the relation between steering axle errors and speed. This graph is included due to the frequent use of steering axle weights of Class 9 vehicles for calibration. This site does not use auto-calibration. The steering axles in this graph are associated only with Class 9 vehicles.

From the figure, it appears that the equipment underestimates steering axle weights at all speeds. The underestimation appears to decrease slightly as speed increases. Variability in error appears to remain fairly constant over the entire speed range.

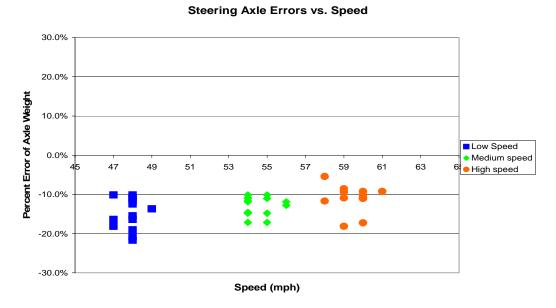


Figure 6-9 Pre-Validation Steering Axle Percent Error vs. Speed Group - 530200 – 28-Nov-2006

Figure 6-10 shows the differing tandem axle errors by truck over the speed range. From the figure, it can be seen that the equipment generally underestimates the tandem axle weights at all speeds. The underestimation and variability in error appears to be greater for the Golden truck when compared with the Partial truck.

Tandem Axle Errors by Truck and Speed

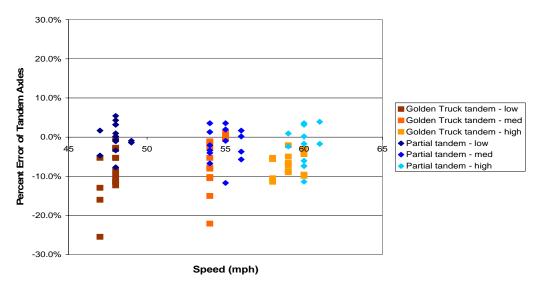


Figure 6-10 Pre-Validation Tandem Axle Percent Error by Truck and Speed – 530200 – 29-Nov-2006

6.3 Classification Validation

This site uses the FHWA 13-bin classification scheme and the LTPP classification algorithm, mod 3. Classification 15 has been added to account for unclassified vehicles.

The classification validation is intended to find gross errors in vehicle classification, not to validate the installed algorithm. A sample of 100 trucks was collected at the site. The classification identification is to identify gross errors in classification, not to validate the classification algorithm. Video was taken at the site to provide ground truth for the evaluation. Based on a 100 percent sample it was determined that there are 1.0 percent unclassified vehicles. The single unclassified vehicle was a Class 8 Vehicle that was classified as a Class 15 because of a slightly light (3,400 lbs) fourth axle when the minimum axle weight for a Class 8 for the algorithm at this site is 3,500 lbs.

The second check is the ability of the algorithm to correctly distinguish between truck classes with no more than 2% errors in such classifications. Table 6-4 has the classification error rates by class. The overall misclassification rate is 1. percent.

Table 6-4 Truck Misclassification Percentages for 530200 – 28-Nov-2006

Class	Percent Error	Class	Percent Error	Class	Percent Error
4	N/A	5	N/A	6	0
7	0				
8	50	9	0	10	0
11	0	12	0	13	0

The misclassification percentage is computed as the probability that a pair containing the class of interest does NOT include a match. Thus if there are eight pairs of observations with at least one Class 9 and only six of them are matches, the error rate is 25 percent. The percent error and the mean differences reported below do not represent the same statistic. It is possible to have error rates greater than 0 with a mean difference of zero.

Table 6-5 Truck Classification Mean Differences for 530200 - 28-Nov-2006

Class	Mean	Class	Mean	Class	Mean
	Difference		Difference		Difference
4	N/A	5	N/A	6	0
7	0				
8	-50	9	0	10	0
11	0	12	0	13	0

These error rates are normalized to represent how many vehicles of the class are expected to be over- or under-counted for every hundred of that class observed by the equipment. Thus a value of 0 means the class is identified correctly on average. A number between -1 and -100 indicates at least that number of vehicles either missed or not assigned to the class by the equipment. It is not possible to miss more than all of them or one hundred out of one hundred. Numbers 1 or larger indicate at least how many more vehicles are assigned to the class than the actual "hundred observed". Classes marked Unknown are those identified by the equipment but no vehicles of the type were seen the observer. There is no way to tell how many vehicles of that type might actually exist. N/A means no vehicles of the class were recorded by either the equipment or the observer. The large mean error rates for Class 8s in Table 6-5 reflect the small number of Class 8 vehicles (2 observed), one of which was classified as a type 15 due to a light fourth axle (3,400 lbs) which is 1,000 lighter than what is allowed for a Class 8 vehicle by the classification algorithm.

6.4 Evaluation by ASTM E-1318 Criteria

The ASTM E-1318 criteria for a successful validation of Type I sites is 95% of the observed errors within the limits for allowable errors for each of the relevant statistics. If this site had been evaluated using ASTM E-1318-02 it would not have met the conditions for a Type I site exclusive of wheel loads. LTPP does not validate WIM performance with respect to wheel loads.

Table 6-6 Results of Validation Using ASTM E-1318-02 Criteria

	Limits for Allowable	Percent within	
Characteristic	Error	Allowable Error	Pass/Fail
Single Axles	± 20%	95%	Pass
Axle Groups	± 15%	95%	Pass
GVW	± 10%	88%	Fail

6.5 Prior Validations

There has been no prior LTPP validation of this site.

7 Data Availability and Quality

As of November 28, 2006 this site does not have at least 5 years of research quality data. Research quality data is defined to be at least 210 days in a year of data of known calibration meeting LTPP's precision requirements.

Data that has validation information available has been reviewed in light of the patterns present in the two weeks immediately following a validation/calibration activity. A determination of research quality data is based on the consistency with the validation pattern. Data that follows consistent and rational patterns in the absence of calibration information may be considered nominally of research quality pending validation information with which to compare it. Data that is inconsistent with expected patterns and has no supporting validation information is not considered research quality.

The amount and coverage for the site is shown in Table 7-1. The value for months is a measure of the seasonal variation in the data. The indicator of coverage indicates whether day of week variation has been accounted for on an annual basis. As can be seen from the table, years 1999, and 2002 through 2005 have a sufficient quantity to be considered complete years of classification data. Only years 2003 through 2005 have sufficient weight data. Review of the information provided for the 2004 site validation indicates that the criteria for research quality data were not met due to the variability of the single axle errors. There is insufficient information from the January 2006 validation to determine if the site was providing research quality at that time. As a result at least 5 additional years of research quality data are needed to meet the goal of a minimum of 5 years of research weight data.

Table 7-1 Amount of Traffic Data Available 530200 – 28-Nov-2006

Year	Classification	Months	Coverage	Weight	Months	Coverage
	Days			Days		
1997	30	1	Full Week	28	1	Full Week
1998	160	7	Full Week	141	6	Full Week
1999	216	10	Full Week	173	6	Full Week
2000	161	10	Full Week	152	5	Full Week
2001	135	5	Full Week	172	6	Full Week
2002	297	10	Full Week	117	4	Full Week
2003	358	12	Full Week	242	8	Full Week
2004	301	11	Full Week	237	8	Full Week
2005	267	9	Full Week	273	9	Full Week
2006	194	7	Full Week	199	7	Full Week

GVW graphs and characteristics associated with them are used as data screening tools. As a result classes constituting more that ten percent of the truck population are considered major sub-groups whose evaluation characteristics should be identified for use in screening. The typical values to be used for reviewing incoming data after a validation are determined starting with data from the day after the completion of a validation.

Class 5s, Class 9s and Class 10s constitute more than 10 percent of the truck population. Based on the data collected from the end of the last calibration iteration the following are the expected values for these populations. The precise values to be used in data review will need to be determined by the RSC on receipt of the first 14 days of data after the successful validation. For sites that do not meet LTPP precision requirements, this period may still be used as a starting point from which to track scale changes.

Table 7-2 is generated with a column for every vehicle class 4 or higher that represents 10 percent or more of the truck (class 4-20) population. In creating Table 7-2 the following definitions are used:

- o Class 9 overweights are defined as the percentage of vehicles greater than 88,000 pounds
- o Class 9 underweights are defined as the percentage of vehicles less than 20,000 pounds.
- o Class 9 unloaded peak is the bin less than 44,000 pounds with the greatest percentage of trucks.
- o Class 9 loaded peak is the bin 60,000 pounds or larger with the greatest percentage of trucks.
- For all other trucks the typical axle configuration is used to determine the maximum allowable weight based on 18,000 pounds for single axles and 34,000 pounds for tandem axles. A ten percent cushion above that maximum is used to set the overweight threshold.
- o For all other trucks in the absence of site specific information the computation of under weights assumes the power unit weighs 10,000 pounds and each axle on a trailer 5,000 pounds. Ninety percent of the total for the unloaded configuration is the value below which a truck is considered under weight.
- o For all trucks other than class 9s that have a bi-modal distribution the unloaded peak is defined to be in a bin less than or equal to half of the allowable maximum weight.
- o For all trucks other than class 9s that have a bi-modal distribution the loaded peak is defined to be in a bin greater than or equal to half of the allowable maximum weight.

There may be more than one bin identified for the unloaded or loaded peak due to the small sample size collected after validation. Where only one peak exists, the peak rather than a loaded or unloaded peak is identified. This may happen with single unit trucks. It is not expected to occur with combination vehicles.

Table 7-2 GVW Characteristics of Major sub-groups of Trucks – 530200 – 29-Nov-2006

Characteristic	Class 5	Class 9	Class 10
Percentage Overweights	0.0%	0.1%	3.2%
Percentage Underweights	N/A	0.4%	0.5%
Unloaded Peak		36,000 lbs	36,000 lbs
Loaded Peak		76,000 lbs	100,000 lbs
Peak	8,000 lbs		

The expected percentage of unclassified vehicles is 0.9. This is based on the percentage of unclassified vehicles in the post-validation data download.

The graphical screening comparison figures are found in Figure 7-1 through Figure 7-5. These are based on data collected immediately after the validation and may not be wholly representative of the population at the site. They should however provide a sense of the statistics expected when SPS comparison data is computed for the post-validation Sheet 16.

Class 5 GVW Distribution

50.0% 45.0% 40.0% Weight in 1000s of Pounds 35.0% 30.0% 25.0% Class 5 20.0% 15.0% 10.0% 5.0% 0.0% 12 20 28 36 40 16 Percent per Bin

Figure 7-1 Expected GVW Distribution Class 5 – 530200 – 29-Nov-2006

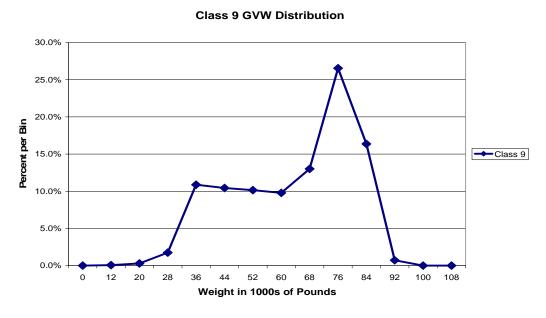


Figure 7-2 Expected GVW Distribution Class 9 – 530200 – 29-Nov-2006

Class 10 GVW Distribution

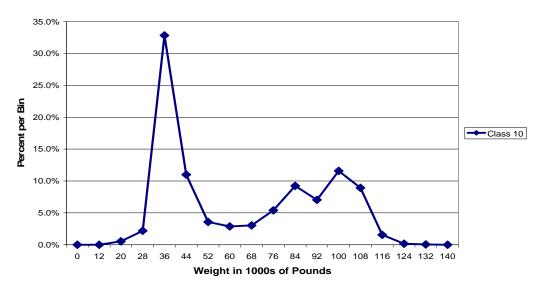


Figure 7-3 Expected GVW Distribution Class 10 – 530200 – 29-Nov-2006

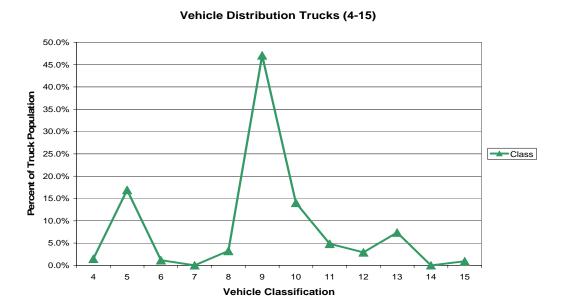


Figure 7-4 Expected Vehicle Distribution – 530200 – 29-Nov-2006

Speed Distribution for Trucks

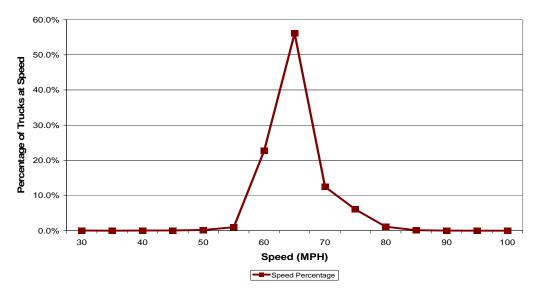


Figure 7-5 Expected Speed Distribution – 530200 – 29-Nov-2006

8 Data Sheets

The following is a listing of data sheets incorporated in Appendix A.

Sheet 19 - Truck 1 - 3S2 loaded air suspension (4 pages)

Sheet 19 – Truck 2 – 3S2 partially loaded air suspension tractor, leaf suspension trailer (4 pages)

Sheet 20 – Speed and Classification verification Pre-Validation (2 pages)

Sheet 20 – Classification verification – Post-Validation (2 pages)

Sheet 21 – Pre-Validation (3 pages)

Sheet 21 – Calibration Iteration 1 – (1 page)

Sheet 21 – Post-Validation (3 pages)

Calibration Iteration 1 Worksheets – (1 page)

Installed Classification Scheme – (1 page)

Final System Parameters – (1 page)

Truck Photographs – (6 pages)

9 Updated Handout Guide and Sheet 17

A copy of the handout has been included following page 35. It includes a current Sheet 17 with all applicable maps and photographs. There are no significant changes in the information provided.

10 Updated Sheet 18

A current Sheet 18 indicating the contacts, conditions for assessments and evaluations has been attached following the updated handout guide.

11 Traffic Sheet 16(s)

Sheet 16s for the pre-validation and post-validation conditions are attached following the current Sheet 18 information at the very end of the report.

POST-VISIT HANDOUT GUIDE FOR SPS WIM FIELD VALIDATION

STATE: Washington

SHRP ID: 530200

1.	General Information	3
2.	Contact Information	3
3.	Agenda	3
	Site Location/ Directions	
5.	Truck Route Information	5
6.	Sheet 17 – Washington (530200)	7

Figures

Figure 4-1 – Site 530200 in Washington	4
Figure 5-1 – Truck Scale Location for 530200 in Washington	5
Figure 5-2 – Truck Route at 530200 in Washington	6
Figure 6-1 - Equipment Layout at SPS-2 site in Washington	10
Figure 6-2 – Site Map for SPS-2 site in Washington	10
Figure 6-3 – Power_Service_Box_TO_17_53_2.83_0200_11_28_06.jpg	11
Figure 6-4 – Telephone_Box_TO_17_53_2.83_0200_11_28_06.jpg	11
Figure 6-5 – Cabinet_Exterior_TO_17_53_2.83_0200_11_28_06.jpg	12
Figure 6-6 – Cabinet_Interior_TO_17_53_2.83_0200_11_28_06.jpg	12
Figure 6-7 – Leading_WIM_Sensor_TO_17_53_2.83_0200_11_28_06.jpg	13
Figure 6-8 – Leading_Loop_Sensor_TO_17_53_2.83_0200_11_28_06.jpg	13
Figure 6-9 – Trailing_WIM_Sensor_TO_17_53_2.83_0200_11_28_06.jpg	14
Figure 6-10 – Trailing_Loop_Sensor_TO_17_53_2.83_0200_11_28_06.jpg	14
Figure 6-11 – Upstream_TO_17_53_2.83_0200_11_28_06.jpg	15
Figure 6-12 – Downstream TO 17 53 2.83 0200 11 28 06.jpg	15

MACTEC Ref. 6420060018_2.83 1/5/2007 Page 3 of 15

1. General Information

SITE ID: 530200

LOCATION: US-395, milepost 93.01, near Ritzville

VISIT DATE: November 28, 2006

VISIT TYPE: Validation

2. Contact Information

POINTS OF CONTACT:

Validation Team Leader: Dean J. Wolf, 301-210-5105, djwolf@mactec.com

Highway Agency: John Rosen, 360-570-2373, rosenj@wsdot.wa.gov

Linda Pierce, 360-709-5470, piercel@wsdot.wa.gov

John Livingston, 360-561-3409, <u>livingj@wsdot.wa.gov</u>

Ken Lakey, 360-570-2374, lakeyk@wsdot.wa.gov

Hoang Nguyen, 360-570-2389, nguyehv@wsdot.wa.gov

FHWA COTR: Debbie Walker, 202-493-3068, deborah.walker@fhwa.dot.gov

FHWA Division Office Liaison: Cathy Nicholas, 360-753-9412,

cathy.nicholas@fhwa.dot.gov

LTPP SPS WIM WEB PAGE: http://www.tfhrc.gov/pavement/ltpp/spstraffic/index.htm

3. Agenda

BRIEFING DATE: No briefing requested for this visit.

ON SITE PERIOD: November 28 and 29, 2006.

TRUCK ROUTE CHECK: Completed at Assessment, May, 2006.

4. Site Location/ Directions

NEAREST AIRPORT: Spokane International Airport

DIRECTIONS TO THE SITE: US-395, approximately 2 miles south of I-90.

MEETING LOCATION: On site beginning at 9:00 a.m.

WIM SITE LOCATION: *US-395*, *milepost 93.01*; *GPS* = *N 47.0737*°, *W 118.4095*°.

WIM SITE LOCATION MAP: See Figure 4.1



Figure 4-1 – Site 530200 in Washington

5. Truck Route Information

ROUTE RESTRICTIONS: None

SCALE LOCATION: Petro Travel Center; I-90, exit 272; Spokane, Washington; GPS = N 47.2115°, W 118.2242.



Figure 5-1 – Truck Scale Location for 530200 in Washington

TRUCK ROUTE: See Figure 5.1

NB on I-395 1.8 miles, merge on to I-90 East for 2 miles, exit 221, left turn to I-395 SB ramp. SB 5.0 miles on I-395 to PAHA/PACKARD exit, left to I-395 NB ramp.

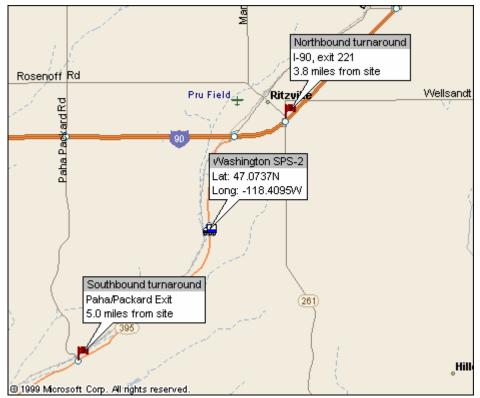


Figure 5-2 – Truck Route at 530200 in Washington

SB distance = 10.8 miles NB distance = 8.4 miles

Total distance = 19.2 *miles* (21 *minutes*)

6. Sheet 17 – Washington (530200)

1.* ROUTE _	I-395	_ MILEPOST _	_93.01_	_ LTPP DIR	ECTION - \underline{N} S E W
Neares	t SPS section te from sens	TION - Grade _ n upstream of the or to nearest upst installed betwee	site ream SP	_0_2_0_5 S Section	
3.* LANE CO					,
	n LTPP dire			Lane width	_1_2_ ft
Mediar	3 - 8	painted physical barrier grass none		Shoulder -	1 – curb and gutter 2 – paved AC 3 – paved PCC 4 – unpaved 5 – none
Should	er width	_1_0 ft			
4.* PAVEME	NT TYPE _	PCC			
Date	Photo	CE CONDITION Filename: Filename:			
		Filename:			
Date	1 11000	1 Heliame			
6. * SENSOR	SEQUENCI	ELoop -	- Kistler	– Kistler -Loc	pp
REPLACI	EMENT AN	D/OR GRINDIN D/OR GRINDIN D/OR GRINDIN	IG	//	′
distanc	ction/drivew e ction/drivew	CTIONS ay within 300 m ay within 300 m	•		_
Is shou	lder routinel	y used for turns of	or passin	g? Y/ <u>N</u>	
9. DRAINAC	SE (Bending	plate and load c	ell syster	ns only)	1 – Open to ground2 – Pipe to culvert3 – None
		ate flush fines from		vstem Y / N	

10. * CABINET LOCATION
Same side of road as LTPP lane \underline{Y} / N Median Y / \underline{N} Behind barrier Y / \underline{N}
Distance from edge of traveled lane _8_3 ft
Distance from system9_0 ft
TYPE M
1112
CABINET ACCESS controlled by LTPP / STATE / JOINT ?
Contact - name and phone numberKen Lakey_ 360-570-2374
Alternate - name and phone numberHoang Nguyen360-570-2389
11. * POWER
Distance to cabinet from drop1_6_0 ft Overhead / underground / solar /
AC in cabinet?
Service providerBig Ben Electric Phone number
12. * TELEPHONE
Distance to cabinet from drop1_6_0 ft Overhead / <u>under ground</u> / cell?
Service providerCentury Tel Phone Number800-533-4171
13.* SYSTEM (software & version no.)IRD 1068
Computer connection – <u>RS232</u> / Parallel port / USB / Other
14. * TEST TRUCK TURNAROUND time21minutesDistance _19.2 mi.
14. TEST TRUCK TURIVAROUND time21minutesDistance _17.2 mi.
15. PHOTOS FILENAME
Power sourcePower_Service_Box_TO_17_53_2.83_0200_11_28_06.jpg
Phone sourceTelephone_Service_Box_TO_17_53_2.83_0200_11_28_06.jpg
Cabinet exterior _ Cabinet_Exterior_Box_TO_17_53_2.83_0200_11_28_06.jpg _
Cabinet interiorCabinet_Interior_Box_TO_17_53_2.83_0200_11_28_06.jpg _
Weight sensorsLeading_WIM_Sensor_TO_17_53_2.83_0200_11_28_06.jpg
Trailing_WIM_Sensor_Box_TO_17_53_2.83_0200_11_28_06.jpg
Classification sensors
Other sensors Leading_Loop_Sensor_Box_TO_17_53_2.83_0200_11_28_06.jpg
_ Trailing_Loop_Sensor_Box_TO_17_53_2.83_0200_11_28_06.jpg
DescriptionLoop Sensors
Downstream direction at sensors on LTPP lane
Downstream_TO_17_53_2.83_0200_11_28_06.jpg
Upstream direction at sensors on LTPP lane
Upstream_TO_17_53_2.83_0200_11_28_06.jpg

COMMENTS	Site phone # - 509-659-4100
all ameni	ties 2 miles north in Ritzville, including La Quinta Inn, McDonalds,
Subway, Shell Gas	
COMPLETED RV	Dean J. Wolf
	5105 DATE COMPLETED _1_1_ /_2_8_ / _2_0_0_6

Sketch of equipment layout

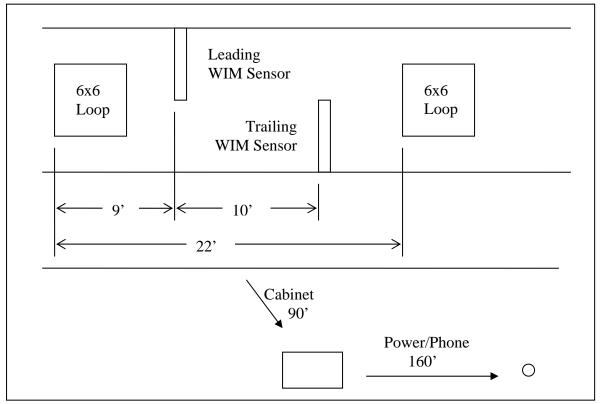


Figure 6-1 - Equipment Layout at SPS-2 site in Washington

Site Map

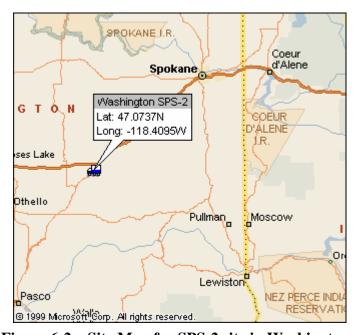


Figure 6-2 – Site Map for SPS-2 site in Washington



Figure 6-3 - Power_Service_Box_TO_17_53_2.83_0200_11_28_06.jpg



Figure 6-4 - Telephone_Box_TO_17_53_2.83_0200_11_28_06.jpg



Figure 6-5 - Cabinet_Exterior_TO_17_53_2.83_0200_11_28_06.jpg



Figure 6-6 - Cabinet_Interior_TO_17_53_2.83_0200_11_28_06.jpg



Figure 6-7 – Leading_WIM_Sensor_TO_17_53_2.83_0200_11_28_06.jpg



Figure 6-8 – Leading_Loop_Sensor_TO_17_53_2.83_0200_11_28_06.jpg



Figure 6-9 – Trailing_WIM_Sensor_TO_17_53_2.83_0200_11_28_06.jpg



 $Figure~6\text{-}10-Trailing_Loop_Sensor_TO_17_53_2.83_0200_11_28_06.jpg$



 $Figure \ 6\text{-}11 - Upstream_TO_17_53_2.83_0200_11_28_06.jpg$



Figure 6-12 – Downstream_TO_17_53_2.83_0200_11_28_06.jpg

SHEET 18	STATE CODE	[_5_3_]
LTPP MONITORED TRAFFIC DATA	SPS PROJECT ID	[_0_2_0_0_]
WIM SITE COORDINATION	DATE: (mm/dd/yyyy)	_1_1_/_2_8_/_2_0_0_6_

1.		ATA PROCESSING — Down load — x State only LTPP read only LTPP download LTPP download and copy to state
	b.	Data Review − x State per LTPP guidelines □ State − □ Weekly □ Twice a Month □ Monthly □ Quarterly □ LTPP
	c.	$ \begin{array}{c} Data \ submission - \\ x \ State - \ \square \ Weekly \ \square \ Twice \ a \ month \ x \ Monthly \ \square \ Quarterly \\ \square \ LTPP \end{array} $
2.	ΕC	QUIPMENT –
		Purchase – x State LTPP
	b.	Installation — ☐ Included with purchase ☐ Separate contract by State x State personnel ☐ LTPP contract
	c.	Maintenance – □ Contract with purchase – Expiration Date □ Separate contract LTPP – Expiration Date □ Separate contract State – Expiration Date x State personnel
	d.	Calibration − □ Vendor x State x LTPP
	e.	Manuals and software control – x State □ LTPP
	f.	$\begin{array}{cccccccccccccccccccccccccccccccccccc$

SHEET 18	STATE CODE	[_5_3_]
LTPP MONITORED TRAFFIC DATA	SPS PROJECT ID	[_0_2_0_0_]
WIM SITE COORDINATION	DATE: (mm/dd/yyyy)	_1_1_/_2_8_/_2_0_0_6_

	g.	$ \begin{array}{cccccccccccccccccccccccccccccccccccc$
3.	PA	AVEMENT –
	a.	Type – x Portland Concrete Cement □ Asphalt Concrete
	b.	Allowable rehabilitation activities − □ Always new □ Replacement as needed □ Grinding and maintenance as needed x Maintenance only □ No remediation
	c.	Profiling Site Markings – □ Permanent x Temporary
4.	Ol a.	N SITE ACTIVITIES – WIM Validation Check - advance notice required2 □ days x weeks
	b.	Notice for straightedge and grinding check - 2 □ days x weeks i. On site lead – □ State x LTPP
		ii. Accept grinding –□ Statex LTPP
	c.	Authorization to calibrate site − x State only □ LTPP
	d.	Calibration Routine – □ LTPP – □ Semi-annually □ Annually x State per LTPP protocol – □ Semi-annually □ Annually □ State other –

SHEET 18	STATE CODE	[_5_3_]
LTPP MONITORED TRAFFIC DATA	SPS PROJECT ID	[_0_2_0_0_]
WIM SITE COORDINATION	DATE: (mm/dd/yyyy)	_1_1_/_2_8_/_2_0_0_6_

5.

e.	Test V i.	Vehicles Trucks – 1st – Air suspension 3S2 2nd –3S2 3rd – 4th –	☐ State ☐ State ☐ State ☐ State ☐ State	x LTPP x LTPP □ LTPP □ LTPP			
	ii.	Loads –	□ State	x LTPP			
	iii.	Drivers –	□ State	x LTPP			
f.	Contra	actor(s) with prior successful expe	rience in WIM	calibration in state:			
		International Road Dynamics (I	(RD)				
g.	Accessi.	s to cabinet Personnel Access – □ State only x Joint □ LTPP					
	ii.	Physical Access – x Key ☐ Combination					
h.	State p	personnel required on site –	x Yes □No				
i.	Traffic	c Control Required –	□Yes x No				
j.	Enforc	cement Coordination Required –	□Yes x No				
	Funds	CIFIC CONDITIONS – and accountability –					
1							
	Report						
		1					
c.	Other						
	N/A						
d.	_	al Conditions –					
	N/A	_N/A					

SHEET 18	STATE CODE	[_5_3_]
LTPP MONITORED TRAFFIC DATA	SPS PROJECT ID	[_0_2_0_0_]
WIM SITE COORDINATION	DATE: (mm/dd/yyyy)	_1_1_/_2_8_/_2_0_0_6_

	α	TT	r .	α	Γ	
h		IIVII	ΓΑ		. `	. —

a.	Equipment (operational status, access, etc.) –
	Name:TDO Ken Lakey Phone:360-570-2374
	Agency:WSDOT
b.	Maintenance (equipment) –
	Name:TDO Ken Lakey Phone:360-570-2374
	Agency:WSDOT
c.	Data Processing and Pre-Visit Data –
	Name:Tony Niemi Phone: _360-570-2392
	Agency:WSDOT
d.	Construction schedule and verification –
	Name:TDO John RosenPhone: _360-570-2373
	Agency: _WSDOT
e.	Test Vehicles (trucks, loads, drivers) –
	Name: Phone:
	Agency:LTPP
f.	Traffic Control –
	Name:TDO_Matt Heathscott Phone: _360-570-2390
	Agency:
g.	Enforcement Coordination –
	Name:N/A Phone:
	Agency:
h.	Nearest Static Scale
	Name: Petro Travel Center Location: I-90, exit 272, Spokane, WA
	Phone:

SHEET 16 LTPP MONITORED TRAFFIC DATA SITE CALIBRATION SUMMARY

*STATE ASSIGNED ID $[_P_C_7_]$ *STATE CODE $[_5_3_]$ *SHRP SECTION ID $[_0_2_0_0_]$

SITE CALIBRATION INFORMATION

1. * E	DATE OF CALIBRATION (MONTH/DAY/YEAR)	[_1_1_/_2_8_/_2_0_0_6_]
2. * Т	YPE OF EQUIPMENT CALIBRATED WIM	CLASSIFIERx_ BOTH
	REASON FOR CALIBRATION REGULARLY SCHEDULED SITE VISIT EQUIPMENT REPLACEMENT DATA TRIGGERED SYSTEM REVISION x_ OTHER (SPECIFY)LTPP Validation	RESEARCH TRAINING NEW EQUIPMENT INSTALLATION
	ENSORS INSTALLED IN LTPP LANE AT THIS SIT BARE ROUND PIEZO CERAMIC BA CHANNELIZED ROUND PIEZO LO. CHANNELIZED FLAT PIEZO x INI OTHER (SPECIFY)	
5. EQ	UIPMENT MANUFACTURERIRD/PAT Traffic	2
	WIM SYSTEM CALI	BRATION SPECIFICS**
6.**CA	LIBRATION TECHNIQUE USED:TRAFFIC STREAMSTATIC SCALE	(Y/N) _x_TEST TRUCKS
	NUMBER OF TRUCKS COMPARED	2 NUMBER OF TEST TRUCKS USED
	TYPE PER FHWA 13 BIN SYSTEM SUSPENSION: 1 - AIR; 2 - LEAF SPRING 3 - OTHER (DESCRIBE)	2_0 PASSES PER TRUCK TRUCK TYPE SUSPENSION 1 9 1 2 9 _2 3
7.	SUMMARY CALIBRATION RESULTS (EXPRESS MEAN DIFFERENCE BETWEEN DYNAMIC AND STATIC GVW DYNAMIC AND STATIC SINGLE AXLES DYNAMIC AND STATIC DOUBLE AXLES	6.0 STANDARD DEVIATION4.2 12.9_ STANDARD DEVIATION3.6
8.	3 NUMBER OF SPEEDS AT WHICH CALI	BRATION WAS PERFORMED
9.	DEFINE THE SPEED RANGES USED (MPH)	50 , 55 , 65
10.	CALIBRATION FACTOR (AT EXPECTED FREE F	LOW SPEED)6.500298
11.**	IS AUTO-CALIBRATION USED AT THIS SITE? (Y IF YES, LIST AND DEFINE AUTO-CALIB	Y/N) _N BRATION VALUE:
	CLASSIFIER T	EST SPECIFICS***
12.***		DLUME MEASUREMENT BY VEHICLE CLASS: PARALLEL CLASSIFIERS
13.	METHOD TO DETERMINE LENGTH OF COUNT	TIMEx_ NUMBER OF TRUCKS
14.	*** FHWA CLASS 850	ES CLASSIFICATION: FHWA CLASS FHWA CLASS FHWA CLASS FHWA CLASS
	*** PERCENT "UNCLASSIFIED" VEHICLES:	1.0
	ON LEADING CALIBRATION EFFORT: _Dean J. Wo	olf, MACTEC Engineering & Consulting, Inc rev. November 9, 199

SHEET 16 LTPP MONITORED TRAFFIC DATA SITE CALIBRATION SUMMARY

*STATE ASSIGNED ID $[_P_C_7_]$ *STATE CODE $[_5_3_]$ *SHRP SECTION ID $[_0_2_0_0_]$

SITE CALIBRATION INFORMATION

1. * I	DATE OF CALIBRATION (MONTH/DAY/YEAR)	[_1_1_ / _2_9_ / _2_0_0_6_]
2. * 7	YPE OF EQUIPMENT CALIBRATED WIM	CLASSIFIERx_ BOTH
	REASON FOR CALIBRATION REGULARLY SCHEDULED SITE VISIT EQUIPMENT REPLACEMENT DATA TRIGGERED SYSTEM REVISION OTHER (SPECIFY)LTPP Validation	RESEARCH TRAINING NEW EQUIPMENT INSTALLATION
	ENSORS INSTALLED IN LTPP LANE AT THIS SIT BARE ROUND PIEZO CERAMIC BA CHANNELIZED ROUND PIEZO LO CHANNELIZED FLAT PIEZO x INI OTHER (SPECIFY)	
5. EQ	UIPMENT MANUFACTURERIRD/PAT Traffic	c
	WIM SYSTEM CALI	IBRATION SPECIFICS**
6.**CA	LIBRATION TECHNIQUE USED:TRAFFIC STREAMSTATIC SCALE	(Y/N) _x_TEST TRUCKS
	NUMBER OF TRUCKS COMPARED	2 NUMBER OF TEST TRUCKS USED
	TYPE PER FHWA 13 BIN SYSTEM SUSPENSION: 1 - AIR; 2 - LEAF SPRING 3 - OTHER (DESCRIBE)	2_0 PASSES PER TRUCK TRUCK TYPE SUSPENSION 1 9 1 2 9 _2 3
7.	SUMMARY CALIBRATION RESULTS (EXPRESS MEAN DIFFERENCE BETWEEN DYNAMIC AND STATIC GVW DYNAMIC AND STATIC SINGLE AXLES DYNAMIC AND STATIC DOUBLE AXLES	0.3 STANDARD DEVIATION3.2 3.7_ STANDARD DEVIATION5.7_
8.	3 NUMBER OF SPEEDS AT WHICH CALL	IBRATION WAS PERFORMED
9.	DEFINE THE SPEED RANGES USED (MPH)	50 , 55 , 65
10.	CALIBRATION FACTOR (AT EXPECTED FREE F	FLOW SPEED)6.690134
11.**	IS AUTO-CALIBRATION USED AT THIS SITE? (YOU IF YES, LIST AND DEFINE AUTO-CALIED	Y/N) _N BRATION VALUE:
	CLASSIFIER T	EST SPECIFICS***
12.***	METHOD FOR COLLECTING INDEPENDENT VO	DLUME MEASUREMENT BY VEHICLE CLASS: PARALLEL CLASSIFIERS
13.	METHOD TO DETERMINE LENGTH OF COUNT	TIMEx_ NUMBER OF TRUCKS
14.	*** FHWA CLASS 850	FHWA CLASS FHWA CLASS
	*** PERCENT "UNCLASSIFIED" VEHICLES:	1 . 0
	ON LEADING CALIBRATION EFFORT: _Dean J. W ΓΑCT INFORMATION:301-210-5105	folf, MACTEC Engineering & Consulting, Inc rev. November 9, 199



Shee		* STATE_CODE	_5_3_
LTPP Tra *CALIBRATION T		* SPS PROJECT ID * DATE	0 2 0 0
Rev. 08/31/01	DOI INOCK # 1	DATE	1 1 / 2 8 / 2 0 0 6
PART I.			
1.* FHWA Class <u></u>	2.* Number of Axles _	5	
AXLES - units -(lbs)/ 100s lb	s /kg		
3. Empty Truck Axle Weight	4.* Pre-Test Average Loaded Axle Weight	5.* Post-Test Average Loaded Axle Weight	6.* Measured D)irectly or C)alculated?
A	12970	\1700	(D) / C
В	15570	15210	Ø / C
C	15570	15210	Ø / C
D	16480	16090	Ø / C
E	७७५%	<u> </u>	6 / C
F			D / C
GVW (same units as axles)			
7. a) Empty GVW	*c) Post Test L	re-Test Loaded weight Loaded Weight Post Test — Pre-test	77060 75310 1750
GEOMETRY			
8 a) * Tractor Cab Style - Cab C	over Engine Conventiona	b) * Sleeper Cab?	Y(N)
9. a) * Make: Fliethliner b) * Model: <u>+LD -D</u>	<u>2</u> 4	
10.* Trailer Load Distribution D		1	
	hipopel brown to stone pr	s.lv	
1)			
11. a) Tractor Tare Weight (unit	s):		
b). Trailer Tare Weight (unit			
5420060018_SPSWIM_TO_17_53_2.	83_0200_Truck_1_Sheet_19.d	oc	

12.* Axle Spacing – units m	/ feet and inches / fe	et and tenths	
A to B 128 B	s to C 4.3	C to D 32.5	Þ
Г	to E	E to F	and the same of th
Wheelbased (measured	A to last)	Computed 5カニ	<u>L</u>
13. *Kingpin Offset From Axle		to the rear)	
SUSPENSION			
Axle 14. Tire Size 15	.* Suspension Descripti	on (leaf, air, no. of leaves, t	caper or flat leaf, etc.)
A 11R22.5		1 tager	
B 1122.5		7	
C 11R22.5	air		
D 295/75R 22.5	<u>air</u>		
E 195/75R 22.5	<u> </u>		
F			
16. Cold Tire Pressures (psi) – 1	from right to left		
	_		
Steering Axle Axle B	Axle C	Axle D	Axle E
	AA		
-			

* STATE_CODE

* DATE

* SPS PROJECT ID

5 3 0 2 0 0

1 1 / 2 8 / 2 0 0 6

Sheet 19

LTPP Traffic Data

*CALIBRATION TEST TRUCK #_1

Rev. 08/31/01

Sheet 19	* STATE CODE	5 3
LTPP Traffic Data	* SPS PROJECT ID	0200
*CALIBRATION TEST TRUCK #_1_	* DATE	11/28/2006

Rev. 08/31/01

PART II

Table 1. Axle and GVW computations - pre-test

Axle A	Axle B	Axle C	Axle D	Axle E	GVW	
I	II	III	IV	V	V	
	-I	-II	-III	-IV		
V -VI	VI- VII	VII- VIII	VIII- IX	IX,	X	
					XI	
Avg.						

Table 2. Raw Axle and GVW measurements

Table 2. Raw Axie and G	v w meas	urements	,
Axles	Meas.	Pre-test Weight	Post-test Weight
A	I		
A+B	II		
A+B+C	III		
A+B+C+D	IV		
A+B+C+D+E(1)	V		
B+C+D+E	VI		
C+D+E	VII		
D+E	VIII		
Е	IX		
A + B + C + D + E (2)	X		
A + B + C + D + E (3)	XI		

Table 3. Axle and GVW computations - post -test

Axle A	Axle B	Axle C	Axle D	Axle E	GVW
I	П	Ш	IV	V	V
	-I	-II	-III	-IV	
V -VI	VI- VII	VII- VIII	VIII- IX	IX,	X
					XI
Avg.					

Sheet 19	* STATE_CODE	5 3
LTPP Traffic Data	* SPS PROJECT ID	0 2 0 0
*CALIBRATION TEST TRUCK #_1	* DATE	1 1 / 2 8 / 2 0 0 6

Rev. 08/31/01

Table 4. Axle and GVW computations -

Axle A	Axle B	Axle C	Axle D	Axle E	GVW	
I	II	III	IV	V	V	
	I	-II	-III	-IV		••••
V -VI	VI- VII	VII- VIII	VIII- IX	IX,	X	
					XI	
Avg.						

Table 5. Raw data – Axle scales – pre-test

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1	12920	15590	15590	16470	10470	e de la constanción de la cons	77040
2	13000	i5550	15550	16490	16490	Animer .	<u> </u>
3	12980	16560	15560	16480	16480	wit 1734-003kg	77060
Average	12970	15570	15570	16480	16480	Messansya	77060
Q#54	12640	15270	15270	16260	16260		75700

Table 6. Raw data - Axle scales - gre - Am 1

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1	13020	15440	15420	16230	16230		76360
2	13020	15440	15440	16240	16240		76380
3	13070	15440	15338	16230	16230		76360
Average	13020	15440	15440	16230	16230		76370

Table 7. Raw data – Axle scales – post-test λ_{M} 2

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1	12620	15260	(5260	16090	16090		75370
2	12720	15200	12500	16090	16090		75300
3	12760	15180	15180	16090	16090		75300
Average	12700	15210	15210	16090	16090		75310

Measured By Verified By

	eet 19 'raffic Data	* STATE CODE	5 3	
*CALIBRATION	TEST TRUCK # 2	* SPS PROJECT ID * DATE	0 2 0 0 1 1 / 2 8 / 2 0 0 6	
Rev. 08/31/01				
PART I.				
.* FHWA Class	2.* Number of Axles			
AXLES - units bs/100s	lbs / kg			
3. Empty Truck Axle Weight	4.* Pre-Test Average Loaded Axle	Loaded Axle	6.* Measured D)irectly or	
A	Weight 	Weight \0360	C)alculated? <u>D</u> / C	
B	<u> </u>	13500	<u>D</u> / C	
C	\3\430	13500	D / C	
D	15030	1500	D / C	
E	১১৫১০	15010	D / C	
F			D / C	
GVW (same units as axles)				
7. a) Empty GVW		Pre-Test Loaded weight	L 8330	
		*c) Post Test Loaded Weight*d) Difference Post Test – Pre-test		
GEOMETRY	,		950	
3 a) * Tractor Cab Style - Cab	Over Engine /Convention	h) * Sleener Cah?	VA	
		namatarore	1 /(1)	
). a) * Make: Friet liner	b) * Model: <u>700 - 0</u>			
10.* Trailer Load Distribution	*			
Concatte degin for	per distributed eventy	slong fisiter		
II. A Taraka Tara III. 147				
11. a) Tractor Tare Weight (u.	nits): nits):			
oj. Hanci Taic Weight (u	шю).			
5420060018_SPSWIM_TO_17_53	_2.83_0200_Truck_2_Sheet_19	9.doc		

CALADICAL.	IOIVIEGI INOCK # Z	1 DAID	11/28/206
Rev. 08/31/01			
12.* Axle Spacing – units	m / feet and inches / f	eet and tenths	
A to B 12.8	B to C4.3	C to D <u>30.1</u>	
	D to E	E to F	
Wheelbased (meas	ured A to last)	Computed5\.\}	
13. *Kingpin Offset From	Axle B (units) 4 (+:	is to the rear)	
SUSPENSION			
Axle 14. Tire Size	15.* Suspension Descrip	tion (leaf, air, no. of leaves,	taper or flat leaf, etc.)
A 11R 22.5	2 fun leaf		
B 11 R 22.5	· · · · · · · · · · · · · · · · · · ·		
C 11 12 22 5			
D 11 R225		z.f	
E 11225	3 taperd 1	eaf	
F		\	
16. Cold Tire Pressures (p	si) – from right to left		
~	· •		
Steering Axle Axl	e B Axle C	Axle D	Axle E

<u></u>			

* STATE_CODE

* DATE

* SPS PROJECT ID

5_3 0_2_0_0

1 1 / 2 8 / 2 0 0 6

Sheet 19

LTPP Traffic Data
*CALIBRATION TEST TRUCK # 2

Sheet 19	* STATE_CODE	5_3_
LTPP Traffic Data	* SPS PROJECT ID	0 2 0 0
*CALIBRATION TEST TRUCK #_2	* DATE	1 1 / 2 8 / 2 0 0 6

Rev. 08/31/01

PART II

Table 1. Axle and GVW computations - pre-test

Axle A	Axle B	Axle C	Axle D	Axle E	GVW
	II	III	IV	V	V
	_I	-II	-III	-IV	
V -VI	VI- VII	VII- VIII	VIII- IX	IX	X
					XI
Avg.					

Table 2. Raw Axle and GVW measurements

Table 2. Raw Axie and G	v vv meas	urements	1		· · · · · · · · · · · · · · · · · · ·
Axles	Meas.	Pre-test Weight		t	Post-test Weight
A	I				
A+B	II				
A+B+C	III				
A+B+C+D	IV				
A + B + C + D + E (1)	V				
B+C+D+E	VI				
C + D + E	VII				
D+E	VIII				
E	IX				
A + B + C + D + E (2)	X				
A + B + C + D + E (3)	XI				

Table 3. Axle and GVW computations - post -test

Axle A	Axle B	Axle C	Axle D	Axle E	GVW	
	II	III	IV	V	V	
	_I	-II	-III	-IV		
V	VI-	VII-	VIII-	IX,	X	
-VI	VII	VIII	IX			
					XI	
Avg.						

	Sheet 19			TATE CODE	5 3	
	LTPP Traffic Data			PS PROJECT ID	0 2 0 0	
*CALIBRATION TEST TRUCK # 2			* D	ATE	11/28/2006	
.ev. 08/31/01 Cable 4 . Axle and	l GVW comp	utations -				

Axle A	Axle B	Axle C	Axle D	Axle E	GVW	
I	II	III	IV	V	V	
	-I	-II	-III	-IV		
V -VI	VI- VII	VII- VIII	VIII- IX	IX.	X	
					XI	
Avg.						

Table 5. Raw data – Axle scales – pre-test

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1	11360	13470	13470	15020	15020	and the state of t	68340
2	11420	13400	<u>13400</u>	15070	15070	No. Co. Co. Co. Co. Co. Co. Co. Co. Co. C	68360
3	11460	13430	13430	14990	14990	وجاندي	68300
Average	410	13430	13430	15030	15030	MST/rs/regenerate	68330
(OST	11060	13320	13320	14990	14990		67680

Table 6. Raw data - Axle scales - grading 2

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1	10880	13590	13590	15000	15000		68060
2	10720	13620	13620	15040	15040		68040
3	10600	13710	13710	15020	05021		68060
Average	10730	13640	13640	15020	15020		68850

Table 7. Raw data – Axle scales – post-test - λ_{k_1} 2

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
<u> </u>	10760	13500	13200	12010	12010		67380
. 2							
3							
Average	10360	13500	13500	15010	15010		67380

Measured By	Verified By_	Antie
-------------	--------------	-------

	· · · · · · · · · · · · · · · · · · ·		Sheet 20			* STATE	CODE			5 3
		LT	PP Traffic I			I	OJECT II	<u> </u>	<u> </u>) 2 0 0
	Speed an		ation Chec		of*	* DATE		1 1 /		006
		31/2001						2000		
	WIM	WIM class	WIM	Obs.	Obs	WIM	WIM	WIM	Obs.	Obs
	speed	Class	Record	Speed	Class	speed	class	Record	Speed	Class
	i	1	273	61	13	/ .	9	1469	962	tr.
	62	13		······································		6	1	1-62-		9
	(d 5	13	1179	68	13	X 54	70	12.12	<u> </u>	10
	65	13	1192	65	13	ÇS	9	1542	64	9
ļ	48	9	1197	48	G ₁	G Z		1766	61	
	44	3	ROB	ŢB.	53	62	19	608/	62	13
		lo	1788	59	10	64	£ 5	ısıı	63	13
	5	9	1235	<u> </u>	<u> </u>	58	8. V.	18039		11
	<u>64</u>	13	1241	<u> </u>	13	60	8	1880	61	8
	Col	13	1252	<u>e</u> l	13	63	~~	1823	62	9
	58_	13	1258	55	13	45	<u> </u>	1891	lo S	9
	57		1282	de la company	3	62	C. Sandy	1916	62	9
		<u>lo</u>	1284	<u>S</u>	10	6/2a	2 ₁	1923	64	3
	bz	9	1302	62	9	Cod		1930	64	
	<u> </u>	10	1357	61	10	65	9	2012	65	9.
•	57	9	1317	See on .	9	ķЧ	\ 2,	2022	(-1	13
	SS	13	1318	SL	13	54	9	2055	54	Ŷ
	Co 4-	9	1340	C A	- 3 1	67	9	7093	66	n
	<i>6</i> 3	11	1344	64	11	65	9	2096	le 4	Ŷ
#	61	15	1366	6	8	57	5	2104	57	5
	60	9	1392	60	9	59	13	2123	59	1 3
	64	10	1399	<u>63</u>	10	63	9	2129	43	9
1	56	13	1414	58	13	59	વ	2,33	60	9
ļ	Lel	13	1420	61	13	45	4	2,44	(N	Cq
	62	10	1429	62	10	W	4	2166	43	9
	61	13	1454	59	13	ķΰ	9	2167	58	. 9
L.	Recorded		1	Dire	ction	Lane	I Time f	rom <u> </u>	in to V	L-22

	***************************************	PP Traffic			*SPS PR	OJECT_II)	ϵ	200	
		cation Chec	ks * 2	of*	* DATE		1_1_/		0 0 6	1
Rev. 08/3 WIM	31/2001		(7)		I YYYTA C	****		T = -	<u> </u>	7
speed	WIM class	WIM Record	Obs. Speed	Obs Class	WIM	WIM class	WIM	Obs.	Obs	
speed	Class	Record	Speed	Class	speed	class	Record	Speed	Class	
_58	9	2221	60	9	60	6	2698	53	6	
60	=	2233	60	9	60	Š	2709	Q0	5	
60		2234	55	~	<u>CQ</u>		2717	59		
60	-3	2247	اپ	9	<u>_\$</u>	5	2754	58	<u> </u>	
49	S	2277	49	9	65	13	2764	64	B	
40	9	2340	60	9	<u> </u>	13	2814	59	13	
62	<u> </u>	2341	62	9	60	9	2820	61	9	
	13	2350	62	13	62	13	28:23	62	10	
64	12	2362	63	12	<u> </u>	12_	2235	1-260	651	2
55	9	2367	54	9	61	<u> </u>	2840	73(0	60	13
55	13	2375	<u> </u>	13	60	la	2843	18560	60	15
59	9	2451	59	9	<u> </u>	13	283	\$3		
50	9	2454	59	9	65	C2-7	78.60	<u> </u>	4	
62	Q	2465	62	Q	63	9	2863	64	9	
62	3	2477	61	9	61	10	2873	رى دى	<u> </u>	
<u></u>	9	2483	<u>63</u>	5 2 ₁	61	10	2885	<u>63</u>	10	
اه	5	2500	6Z_	S	64	<u>a</u>	2901	(64 <u></u>	9	
62		2506	62	3	0 Z	10	2903	61	13	
64	(p	8024	63	C	63	13	2916	62	13	
60	G)	2517	<u> </u>	9	<i>ω</i> 5	C	2917	64	9	
62	9	2651	63	9	60	9	2925	60	4	
ピコ	5	2666	(A)	Š	61-	9	2927	١٥١	9	
62		2675	<u> </u>	<u> </u>	62	9	2900	62	£24	
62	3	2677	62	9_	-G5	5	2957	65	5	
Colo		2689	65		<u></u> 65		2958	<u>65</u>	4	
Recorded	Uy A	6 <u>0</u>	Dire	ection <u>N</u>	_ Lane _	1 11me i	rom /2:23	$\frac{1}{2}$ to $\frac{2\pi}{2}$	45	

* STATE_CODE

al ___

Sheet 20

		Sheet 20			* STATE CODE 5 3					
C 1	· · · · · · · · · · · · · · · · · · ·	ΓΡΡ Traffic I		~		OJECT_II			0 2 0 0	
	ind Classif /31/2001	ication Chec	ks * 1	of* 2	* DATE	· · · · · · · · · · · · · · · · · · ·	1 1 /	29/_	2_0_0_6_	
WIM speed	WIM class	WIM Record	Obs. Speed	Obs Class	WIM speed	WIM class	WIM Record	Obs. Speed	Obs Class	
	13	1637	60	13		6	1985		8	
	<u> </u>	1662	62	<u></u>		3	2507		9	
ki keamerer		Notes		<u> </u>	, , , , , , , , , , , , , , , , , , ,	9	2008		9	
	<u> </u>	1669		9		9	2010	· · · · · · · · · · · · · · · · · · ·	9	
	<u> </u>	1671		= = = = = = = = = = = = = = = = = = = =		<u> </u>	2029		5	
·	9	1679	· · · · · · · · · · · · · · · · · · ·	9		9	2058		9	
	13	1682		13		13	2064		13	
	13	1686		13		10	2069		10	
	13_	1692		13		18	7082		13	
	13	1773		13		<u> </u>	2087		9	
	9	1798		्र प्		9	2095		9	
	5	1834		S		9	2096		9	
·	13	1849		13		9	2102		9	
	9	1867	····	9		9	2104		9	
	5	1870		5		9	2109		7	
	9	1876		9	·	9	2117		9	
	10	1881		100		9	2118		9	
	9	1884		9		વ	2127		9	
	9	ोन = ो		9		9	2128	·	9	
	13	1926		13		9	2141		વ	
	<u>a</u>	1927		9		9	3145		9	
	Gy Gy	1929		•		13	2160		13	
	9	1938		9		١3	2162		13	
	<u>Co</u>	1939		6		9	2172		9	
	9,	1969	, A.	9		9	2183		9	
Recorde		1969 Jabie		ection N	Lane _		2185 from <u>18:30</u>	<u>) to 1</u>	<u>1</u> 1 2:42	



Sheet 20 LTPP Traffic Data						* STATE_CODE *SPS PROJECT_ID				
Speed a		cation Chec		of* 2	* DATE	29/	0200			
Rev. 08/	/31/2001	•				-				
WIM speed	WIM class	WIM Record	Obs. Speed	Obs Class	WIM speed	WIM class	WIM Record	Obs. Speed	Obs Class	
	9	2190		9			2440		F4 3	
	9	2191		9		=	2442		9	
	13	2207		13		9	2444		9	
	4	2209		Ý			2450		S	
	9	2305		9		<u> </u>	2454		9	
,	*5	2320		5		57	2458	***************************************	3	
	9	7323		<u> a </u>			2465		5	
	13	2329		413		9	2467		9	
	9	2330		9		<u> </u>	2414		6	
	9	2355		4		4	2476		4	
	12	2844		<u>lz</u>		9	2480		9	
·····	9	<u> </u>		- 9		9	2405		9	
·····	9	2365		91		9	2488		9	
		2367		دخن		15	2490		8	
	9	2403		O.		13	2492		13	
	9	2407		9		9	2496		a	
	10	2409		(0		a	7497		9	
	5	2411		5		123	252=		13	
	13	2412) 3		4	2527		<u> </u>	
	9	2413		9		125	25257		13	
	10	2414		10		10	2552		10	
	12	2417	***************************************)2		10	2562		lo	
—————————————————————————————————————	10	2424		10		9	2513		<u> 9_</u>	
	5	24(27		5		<u> </u>	2575		<u> </u>	
	5	2428 ~bie		5		9	2590		9	



Truck-1-11860 Truck-2-68330

				E-F space																	
				D-E space	Ŧ	1 1	*	<i>(</i>)	()	4	4			0	7	4	1		vinnen.		
5 3	0 2 0 0	, 0		C-D space	K. K.	R	33.0	7:08	0 A	30.5	S,	L	78	8.5	(N)	\ \\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\	3.5		1	26.3	
)	2.8	11	B-C space	3	4:2		m		4.3	ů	4 4		4.3	4.3	4.3	1 43	-	· ·	5	
		111		A-B space	Į Ž	2	رن ن	o co	5	<u>3</u>	Ţ	, result	5.2	G d	6-71	<u>0</u>	· .		7000 71	12.9	1
CODE	CT ID	il		M/9	į	ů Š	74.2	0 0 0	ć	艺	Ī	- 9 3	\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \	63.1	No.	 	1 00	<u>r</u> 29		٠ 3	,
STATE O	1	* DATE		Axte F weight	Ĺ,	١	فتحق	}	200	j											1
*	*SP	*		Axle E weight.	5.5	5	15:8	15.2	(i)	ام ا	() <u>1</u>	ي ق	4	ę Ę	7	9	N.	6.3	52	2	-
				Axle D weight.	89	0	(b.8	က်	j. O	52	1	ر د	2	<u> </u>	j	4	r.	À	9-71	in the second	
				Axle C weight.	Ž	Ş 0	15.7	, 69 (9	<u>ب</u>	Ž	, y		15:21	6.2	<u>'</u>	6.4	2	13.8	(7)	er O	
		3		Axle B weight.	K :3	0	s. b	50	9	رن 0	颂	12.5	Š) Č	Š	5	9.51	177	Contract Con	3.5	-
		to !		Axle A weight.	r i	J.	o o	o()	و	9.2	بر ا ند	, . , <u>.</u>	9.01	٥		,	4.1	σ (†) ∞ Ω	lo. b	o o	
21	ic Data	scords		WilM Speed	\$	5	Y	N	S N	<u>ن</u> و	ŗ	46	N N	3	9	0 Q	\$	4, Q	<u></u>	泛	
Sheet 21	LTPP Traffic Data	est Truck Records		Record No.	E	7208	523	723.7	दिवद	S		1887	Lange Care	2 2 2	<u>0</u>	् <u>छ</u> ८८	19 2%	243	5597	Š	
		System Test		Time	# 100 0	7	4.	70,00	4. V. O	(3,53,0)	12 12 12 12 12 12 12 12 12 12 12 12 12 1	₹, **, **, **,	6,	7.40.1	ET.		₹\$. 10,		5,20.2)	10.00	
		WIM Sy		Pass	a)jgazza	- New	J	2	M	7		· 4	М	У	0	و	· fin	,	œ		
				Truck		7	samuqui ^{na} -	2	white	2	,,,,,,,,,	d			o Sacrotolia	١	a lipsolare	2	and the second second	Ċţ	
			Rev. 08/31/2001	Radar Speed	3	(A)	8	0 N	νυ Ω	Į.	T	왕	Ŋ	82/	0	S	\$ 0	Ø V),	35	:
			Rev. 08	Pvm.t temp	寸		7. N	ž	3	و.	90	<u>w</u>	10 m	\$. V	7	3 Jan.	Š	2	3	

6420060018_SPSWIM_TO_17_53_2.83_Pre_Val_Sheet_21.doc

Checked by

Recorded by Ambic

				E-F space											1					
		9	100=-	D-E space	٥ ٦		7	4	ż	4 (i	4	0 .j	4.0	7	4:0	Ą	つう	Į.,	Ţ	4.
53	0200	2000		C-D space	33.1	30.00	33.2	30.1	32.8	\$-aE	88	V. (0 (V)	3,	708	6.28	36-6	(N)	30.6	33.2	* 20 +
		/ 28/	II.	B-C space	~	r)	4 50	4.2	į.	43	4.5	ない	4 V	÷	43	4 , 5 ,	4.3	7	ナ ナ	, t,
				A-B space	7.9	2.7	s,	- 83	<u>7</u> 80	2	12.8	12.8	5.0	12.3	1	5	6.2	ć	ري ري	500
CODE	ECT ID			0.0W	٦٥. ۲	5	Ď		12.5	bec	20.00	<u>ति</u> १ १	2:13	وي وي	72.9	500	, o	S S	Ü .9	で、対
STATE C	*SPS PROJECT_ID	* DATE		Axle F weight														;		
*	IS*	*		Axle E weight.		7.5)	Š	الما الما الما الما الما الما الما الما	5,0	5 · B	~~~ ~~	و [را	ŗ	c 5	رن	Þ	7	r. 9	0.0	Ñ
				Axle D weight.	639	ن	<u>.</u>	() ()	-	ر م	Ş	و <u>ن</u>	o 날	2	1.5	<u> </u>	Ę.	5 00	7	5 Š
				Axle C weight.	27	L.	3		Ĭ.	5 6	4	ふ	2,5	Č	S S	5	ر د د	ر ت	2	2
	,	eV.		Axle B weight.	<u>ب</u> م	3	15.4	Ý	ナシ	44.1	0 9	50 25	4	2	15.4	っさ	5.3	ار کو:	13,2	2
		jo 🚆		Axle A weight.		0.0		8, W	Ż	و ص	er L	<u>6,</u>	r _o	đ	\\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\	0:0	· V	, o	r.o	6
21	fic Data	ecords		WIM Speed	9	و	¥	4	72	SS	(n)	0	Æ	2	73	4	0	6,	Ţ	.
Sheet.	LTPP Traffic Data	Test Truck Records		Record No.	13	7160	582	2203	287	25 25 25 25 25 25 25 25 25 25 25 25 25 2	2489	7.2	R Roy	26.23	2740	2159	1860 1086	7887	2987	3015
	-			Time	E 12.2)	5,8,0	23	£ 3. 2.	57,70.53	(3,0,0)	2, '2, '0	الم الم		O. Tr. C	2 Co.	14.26.17	\$ P	3.		4.17
		WIM System		Pass	<u>a_</u>	0	0	0		, section 4		2		0	7	4	2	2	2	2
		111111111111111111111111111111111111111		Truck	and department	H		4	grana	4	duste	d	. parente	\sim	سميسد	7	41HHAMA	لۍ	- XXXXXXIII	2
The second secon			Rev. 08/31/2001	Radar Speed	8	3	Ñ	3)	3	7	φ <u>γ</u>	٥ 2	40	3	4	v V	9	2	7	
			Rev. 0	Pvmt temp	3		313	000	Š	<u>``</u>	3		1	3	. ~	7	13.5	13:5	25	Siz

6420060018_SPSWIM_TO_17_53_2.83_Pre_Val_Sheet_21.doc

Checked by

Recorded by

					Sheet 21	21					* ST	* STATE_CODE	ODE			53		
					LTPP Traffic Data	fic Data					*SP:	*SPS PROJECT	CT ID			0200		
Rev 08/31/2001	1001		VIM Sys	WIM System Test Truck Records	Truck R.	ecords	% of	(2)			* D1	* DATE		1 1	28/	2006		
Pvmt Radar temp Speed		Truck	Pass	Time	Record No.	WIM Speed	Axle A weight.	Axle B weight.	Axle C weight.	Axie D weight.	Axle E weight.	Axle F weight	@vw	A-B space	B-C space	C-D space	D-E space	E-F space
23, 52				3,0,5	7000	t	Ę	から	0-1-0	2	0.5		3.	52	7	8	سي.	
3 5 82		a		(6,0,3)	25.00	N.	g g	13,0	ټ ق	13. G	5.3		و ن 9	6.2	7.7		"T"	
20			30	5.04.15	3240	S	, iii.	+ ± + ± + ± + ± + ± + ± + ± + ± + ± + ±	j	÷	7 <u>1</u>		1 0	2.8	į.	32.9	4:0	
お <u>く</u> 49	2		Ñ	3.03.0	G M	40	r.	2	20 50	Ď Ť	16.2		Q O Q	6.21	43	25	のナ	
37.00	- a		ā	\$1. 'A'	22.5	9	2	9	0.61031	てす	Ę W		683	13.0	4	W 0,0	and the same	
1500 <4			9	C. Xo.	SABY	こ	<u>(</u>	4.0 2.4	·	7	0 52		Q (2)		∿ t	32.9	may.	
4000	7	٩	(0) Tri		Š,	27	d G	و 2	13.5	Š	7. V		639	12.9	1		1	
2	5	7	7	(S. S. S.	30.5	ν Ω	,	o Ė	<u>a</u>	0	+5	.	10.0	J O		33.	3	
2	ر		0	95.	Z R	Q	Ö	2	F. 2	00	<u>3</u>		63.0	13.0	4		Ź	

Recorded by	ȳ.							Checked by	by	2								
										tal	r							

	7		***************************************	50°1	7. 5. 2. Balan						Truck-2	١ ١	680S		1020 10730					
		THE REAL PROPERTY OF THE PERSON OF THE PERSO			,	Sheet 21	21					* ST	STATE CC	CODE			5.3			
				1		LTPP Traffic Data	fic Data	***************************************				\$dS*	*SPS PROJECT	CT_ID		*	0200			
		1		WIM System	stem Tes	Test Truck Records	ecords	Jo	T. CALLES	***************************************		* DATE	VTE		11/	2.9 /	2006			
	Rev. 08	08/31/2001	- -	1	i		ļ.				and the second									,
	Fem of the control of	Kadar Speed	<u> </u>	Pass	Lime	Record No.	Speed	Axle A weight.	Axle B weight.	Axle C weight.	Axle D weight.	Axle E weight.	Axle F weight	@VW	A-B space	B-C space	C-D space	D-E space	E-F space	
	3	23		74	0,3,5	[3	3 48	12-5	9.52	1.2	6:3		,	74.2	12.2	4.3	33.5	Ť		
	٤	7	7		J.33,34	1145	4	0)	9:+1	2 C	i	[:2]	3.5	4.3	30.8	0.7		
	رې (۲	ġ	,	4	87.75.162	2 5 5 6	24	3,2		<u>۲</u> ۲	0.9	(b.2	Ų	35.2B	12.5	4.2	32.7	÷		
	20	53	7	7	هي. المي الم	1271	53	,	ナ	下で	14:32	[b.5]	١	10.9	13.3	4.3	30.7	4.0		
	72	0		ý	12:2:0	1367	و و <u>.</u>	12.5	ه ه	(5.3	6.5	<u>و</u>	(7 6.0	P- 21	4.3	3≥%	4-)		
	77		Ŋ	W	12.0	583		1	14.9	(46	, 主	6.9	(<u>j</u> Ė	5	4.3	30.9	4.1		
	23	, ,		₹	8.36.0 V	14.16 10.116		23	<u>.</u>	15.4	ر. ما ا	15.3	ı	つかい	ر)	4.3	33.1	(, †		
	23	ر 4	7	4	34,34	74 1482	9	ナ ニ	Ę Ś	チュ	ر ب	ا د د	,	72.5	13.1	t %	30.9	j		
	25	ZS.	مستعير	M	4.50	15.74	र्द	<u> </u>	ģ	<u>م</u> ا <u>ن</u>	9.5	7,91		7514	12.9	4.3	32.8	Ç, D		1
	2	0	7	W	5,75,0)	1585 +	Ç Q	7.0	€ 6	ا د د	13.8	<i>a</i> Q (2)	ł	0 0 0	· ·	4.3	30.9	4.)		-18
G	27	SS		و	13051;V	20 20 20 20 20	SS	ガル	15.8	15.E	16-8 (5.5	S. S.	i	16 o	(2.5)	ナ・カ	33.0	4		. در
	2	63	7	و	11.14.39	7 0	63	ナる	ر ج	14.8	13.5	18,3		2.1.9	8,2	ナル	30.7	1.4		
	ļ	48	shive		Z. 1-6-1-1	188	48) 1:- G	ار الار	5,3	1.2	F.9	/	72.0	6-71	ن س	32.9	(·		
	7.7	S	ړ	r	20.5C:\\	800 0	S)	<u>.</u> e.	÷	14.5	たら	16.7	,	۲۰۵۲	ر د د	4.3	30.8	4.0		
	Ž,	35.5		0)	P. E. D.	1089	S.S.	1,2	<u>8</u>	7 7	ا ا و : ک	ا ا	, <i>t</i>	252	12.9	4.3	50 50 50	ń		
	67	Į,	7 -	90	1.54.3.	- 00°- 50°-	7	2.0	r Š	13.8	8.2	15.8	1	9 9	13.0	t.y	357	Ţ. 4		
	Recorded by	ted by	_}	a) d		***************************************		J	Checked by	by				, and the second						

できょう

					as.		•••••					<u> </u>	,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,					ļ					
January.				п	space																		
				D-E	sbace	j	4.0	ナ	4	÷	4.1	7	<u> </u>	0. 3	À	m	7	←	4.0	ू राजी	4		
	53	2 0 0	2006	C-D	sbace	33.0	308	32.7	30.7	33 s	30.9	33.1	30.9	32.8	30.9	33.0	30.7	32.9	30. B	33.0	307		
		0	29/	2-B	sbace	4.3	4.3	4.2		4-3		ţ-3	t, v	4.3		ナ・ナ	43	4.3	رن ن	:3	から		
02/0/ 02/30			11/		space	12.9	[3. is	6.01	13.0	6.2	13.1	(۲	13.1	12.3	(2)	2.8	12-8	12.9	S. S	4 5-21	13.0		
ł	DE	TD		@VW		74.2	12.1	3	8,02°	76.8°		74.b	72.5	1514	1069	76 ò	7	12.5	70.7	2007	 (0) (0)		
. B C C C	STATE CODE	*SPS PROJECT	TE	Axle F	weight		į		;	*	(,		· · · · · · · · · · · · · · · · · · ·	į	ť	•	· • • • • • • • • • • • • • • • • • • •					
9-2-5	*ST	*SP	* DATE	Axle E	weight.	1.31	<u>و</u> 2	(ة ر	ام دیا	<u>9</u> <u>ě</u>	6.9	15.3	اه نځ	الم الم	40 50 50	ر ري ري	18,3	g ±	16.7	6.3	5.8		,
Inck	**************************************			Axle D	welght.	6.31	e +	0.0	5.4.3	(7.9	+	0	δ' '	5.0	1	ا أ رئ	13. S	1.21	シュ	10.5	8	A	
				Axle C	weight.	1-31	4.9	٤ ک	した。	15.9	9-7-	ر د	4.9	و ن	14.8 14.6 13.3	15.6	4.00	15.3	14.5	バング	13.0	by	
				Axle B	welgnt.	الخ.	9	ソ・ソ	サチ	0.0	ب ن	L:5	(4.8	ا ج	g 77]	15.8	ائر اج ئر	٥	÷	85		Checked by	
			J0	Axle A	welgnī.	12-5	. 0	B.2	,	12.5	<u></u>	2.3	<u>+</u>	ر ا	+ 0	12:7	4,5	و ن	<u>0</u> .8	12.1	å	0	
	1	c Data	cords	MIM	obeed	48	45	24	53	9	2	47	97	524	00	S	63	46	SO	ν. Γν	- r.a		
(1) (2) (1) (2) (3)	Sheet 21	LTPP Traffic Data	Truck Records	Record		133	1145	りとら	1121	-	7	14.1e	7.847	574	Š	2000	0171	- 00 00 00	0000	280	303		
9 3	i b		Test	Time		2,2,0	5.58.50 1.	\$15.5°	82, TO 8	12.2/2	10 15 W	2000	10:34:34	at Sign	\$2, 4° 50	1.1/36 P	PS: 711.11	\$. 76:1V	30.36.11	6.5.3	1.54°3		
50°C			WIM System	Pass		4	-صنبصين	2	7		W	4	4	V	W	0	٥	r	r	00	Qo	3	
				Truck			2		4		7		7	نب	7		7	, phore i	لئ		7 -	,	
			10001	N8/31/2001 Radar	naado	3	4,0	さ	53	9	3	1	4.6	S.4	0	S	E3	40	SO	\$\$\$	ارا د	ed by	
+			000	Rev. 08/ Pvmt		2	2	20	22	72	77	23	23	ć,	2	67	27	Ç	7.1	2	67	Recorded by	
· .				<u> </u>			L.	L_	L	<u>I</u>	L		L	i					1				

てなっこうから

1-1874

٠.				E-F space												***************************************					
		9		D-E space	÷	4	÷	o f	4.1	+	+	4.0	-augu-	+		4	¥	+	÷	- Sept	
5 3	18 ()	2 0 0		C-D space	32.9	30.9	33.1	30.7	32.9	30.9	33·0	3i.0	33 ≈	25.7	2.66	F. 08	, E	100%	33.0	30.00	
		29/		B-C space	4.3	M 4	W	7 7	4.3	4.3	\$	€ 5	4.3	4	4	4	4-,3	43	43	4	
		11		A-B space	12.9	5.0	ر ارد	0.5	12.9	5 2	7.7	S.O	7		6 2	1.61	12-3	(23)		0	
CODE	CT ID			MM9	187	Gris	72.8	12	76.5	7,99	24.6	ત. જો	13.c	703	16.8	7	ر ئ		いなった。	K jo	
STATE CO	-	* DATE		Axle F weight														•			
* S.	*SP	ŽQ*		Axle E weight.	15.3	رز	(v)	5.5	ر اق	7.4	Ĭ5.5	ۏ	2) <u>+</u>	9	ر د د	ŗ Ĵ	<u>ل</u> چې	. (5	16.2	5	L.,
				Axle D weight.	و	- 6	<u>ي</u> د ج	3.6	7-91	4	0.0	7		<i>₩</i>	a Ė	(3.8	S - B	\? \?	رب رب	٢	3
				Axle C weight.	5.31	5. Ø	0.5	さい	5.00	0.4	וניע	7	15.7	7	٥	N F	ナニ	ņ	() () () () () () () () () () () () () (14.2	by
		cv.		Axle B weight.	15.9	3.6	5	13.7	15.8	3.	و ف	was	5.3	Ť	ام في	رد	6,3	13.9	3.07	3 0	Checked by
		2 of		Axle A weight.	12.4	4	دستان و مستان سستان	7.01	なった	7	7.1	<u>0</u>	7:71	6	<u>,</u>	0	8)	g ç	مِيْ	0	0
	c Data	cords		WIM Speed	v, Q	2	5	ß	d S	ر ا	S	3	45	N O	4	S	So.	20	<i>3</i>	S	
Sheet 21	LTPP Traffic Data	Test Truck Records		Record No.	2014	2035	2128	2747.	543	, 72.57	2348	23.67	24865	7497	202	2,630	2729	2747	9228	28.5	7
	LT	tem Test		Time	5,5	وازمان	10,74°,50	1.35.31	6.55.5	35.45.5	7. 2.	12:57:57	2 7 TE 2	\$. 5° 5°	3.5.15	13:33:17	(4) e 14	(S, V, V)	1. (2) A	60 A	, 7
		WIM System		Pass	o-	o	0	0	ensie Jenese	- Caracan Cancan Caracan Cancan Cancan Cancan Cancan Cancan Cancan Cancan Cancan Can Cancan Can Can Cancan Can Cancan Cancan Cancan Can Can Can Can Can Can Can Can Can C	2	2	0	D		ナ	Ñ	20	9	9	
The state of the s				Truck	alle et al.	2		را	***	2	, quagraphic	ل	descap	Ŋ		7		7	********	એ	
			Rev. 08/31/2001	Radar	S.	2	Ţ	B	かい	<u>و</u> د	S.	62	4	9	25	Ţ,	S)	Ġ3	\$	ę,	led by
			Rev. 08	Pvmrt	ردم ور	رن الن	2	27	2.9	57	7.0	2,	2	20	in ch	2	2	3	9	2	Recorded by

				E-F space							n and a second						To the second se
				D-E space	4	and t		-	j	4	0 V	0					
5 3	0200	2006		C-D space	23.0	? ?	% % 0	30.8	32.5	r ag	27.78	36.3					
		29/		B-C space	4 4	4 %	4	4.2		4.2	4						
				A-B space	5.2	w	B 7	1.51	12.9		7-21	(2)					
ODE	CT_ID	7,000		@VW	4	Q 0 C	73.6	60.39	Ę	SP3	15.8	C-169					
* STATE CODE	*SPS PROJECT_ID	* DATE		Axie F weight										***************************************			
* S.	$^*\mathrm{Sb}$	* D		Axle E weight.	5	16.3	6.31	15.6	9) F	j	6)	سسير. او سمين					2
				Axle D weight.	7.8 8	14.3		12.3	(J)	介土	ナック	<u>~</u>					Curich
				Axle C weight.	0.2	14.3	15.3 14.3	14.0	13. 50.	Š		す					1 by
		3		Axle B weight.	S:0	t d	<u>5</u>	13.4 13.4	2	ţ	16.3	1					Checked by
		3 of		Axle A weight,	5	6	<u>8</u>	0.0	ू इ	0	9	2					_
21	ic Data	cords		Speed	V	G	an C	_ ~	Ð	4	K	Ŋ					
Sheet 21	LTPP Traffic Data	Truck Re		Record No.	2977	29.6%	7. Seale	3153	323	浴。	i ki	\$ \$0 \$0					ار ا
		tem Test		Time	18 (A)	\$ 50 m	6.00 th	(5.0):S	\$	5.00 m	\$.0°	5.52.8			•		9
		WIM System Test Truck Records		Pass	Ŀ		0)	ā	۵	5	- 0	0 5					
		,		Truck		e	مسمدر	N	مصيدي	J	سندېبندي ۇپ	2			·		
			Rev. 08/31/2001	Radar Speed	2		8,	2		5	× ×	5					Recorded by_
			Rev. 08	Pvmt temp	<u>[</u>	Ü	(h)	S	9 3)	ß	6 7	X					Recor

6420060018_SPSWIM_TO_17_53_2.83_Post_Val_Sheet_21.doc

3.11.2. Iteration 1 Worksheet

Date W 29 Ob

Beginning factors:

Speed Point (mph)	Name	Value
Overall		
Front Axle		
1 – (80 km)	50 mg h	6.500298
2 – (loo kry)	V3 min	6.500218 4.500218
3 - (120 kgs)	75 mon	6,500293
4-()	dyarne	91
5 – ()	1	

Errors (Pre-Validation):

	Speed	Speed	Speed	Speed	Speed
	Point 1	Point 2	Point 3	Point 4	Point 5
	(80)		(100)		(yzo)
F/A	-15%		-13%	· ·	-10°to
Tandem	-5%	<u></u>	- 3 %	3	-5%
GVW	-5 °W		-5 %	(-590

Adjustments:

Overall \square	entage
The state of the s	
Front Axle	1 %
Speed Point 1	o "ใ _ข
Speed Point 2 \square 3.1	40
Speed Point 3 \square 3 .) "h,
Speed Point 4	
Speed Point 5	

End factors:

Speed Point (mph)	Name	Value
Overall		
Front Axle		
1 - (80 kg/s)	50 min	6.690(34
2 - (180 kg/c)	63 non	4.696134 6.696134 6.696134
3 - (120 /2pm)	75 mm	6.690134
4-(dynamic	99
5 – ()		

Task Leader Initials:

ETG LTPP CLASS SCHEME, MOD 3

Axle 1	Weight Min. *	TITY I						2.5				2.5	3.5	3.5			2.5	3.5	5.0	3.5		2.5	3.5	5.0	3.5	3.5	3.5	5.0	5.0	5.0	5.0	5.0
Gross	Weigin Min-May	Treet, rever	0 40 2 00	0.10-5.00	1.00-7.99	1.06-7.99	12.00 >	8.00 >	1.00-11.99	1.00-11.99	20.00 >	12.00-19.99	12.00 >	20.00 >	1.00-11.99	1.00.11.99	12,00-19,99	12.00 >	20.00 >	20.00 >	1.00-11.99	12.00-19.99	12.00 >	20.00 >	20.00>	20.00 >	20.00 >	20.00 >	20.00 >	20.00 >	20.00 >	20.00 >
Spacing 8										·																						3.00-45.00
Spacing 7	· · · · · ·																														3,00-45.00	3.00-45.00
Spacing 6	DWW-11-11					77-10/2-10-10-10-10-10-10-10-10-10-10-10-10-10-																								3.00-45.00	3.00-45.00	3.00-45.00
Spacing 5						***************************************		and the desirement of the state																			4 7 7 4	2,30-10,39	00.02-00.11	3.00-45.00	5.00-45.00	3.00-45.00
Spacing 4						w.L.										7777				1 00 14 00	1.00-11.99	1.00-11.23	7 60 11 00	12 00.27 00	7 50 6 30	11 00 37 00	7 20 11 00	6 00 24 00	3027-00.0	3.00-45.00	3.00-45.00	3.00-45.00
Spacing 3		***************************************												1 00 11 00	1.00-11.99	1 00 30 00	7 60 12 00	13 00 20 00	2 50 20 00	1.00 11.00	1.00-11.23	2 50 6 20	64.0-07.22	6.30-50.00	250630	00.00 AC. 60 A	6 10 50 00	11 00 16 an	2 00 15 00	2.00-42.00	3.00 45.00	3.00-42.00
Spacing 2								6.00-25.00	6.00-25.00	3.00-7.00	6.30-30 00	2.50-6.20	11 00 45 00	00.34 00.44 A	6.00-30 00	6.30-40 00	2.50-679	2.50-6.20	8.00-45.00	6.00-25.00	6.30-35.00	2.50-6.29	2.50-6.29	2.50-6.29	16.00-45.00	11.00-26.00	2.50-6.30	2.50-6.30	1 00-45 00	3.00.45.00	3.00 75.00	2007-2000
I Superior	Proposition of the second seco	1 00 5 00	66.0-00.1	6.00-10.10	10.11-23.09	23.10-40.00	6.00-23.09	6.00-10.10	10.11-23.09	23.10-40.00	6.00-23.09	6.00-23.09	6.00-23.09	6.00-10.10	10.11-23.09	6.00-26.00	6.00-23.09	6.00-26.00	6,00-26.00	10,11-23,09	6.00-23.09	6.00-23.09	6.00-30.00	6.00-30.00	6.00-30.00	6.00-30.00	6.00-26.00	6.00-26.00	6.00-45.00	6.00-45.00	6.00-45.00	2012
Axles		•	4 (?	7	ra	7	-	643	67	6	F.	3	-	4	***	4	4	7	w	160	un	×	5	10	'n	9	9	r	90	6	
	To the second se	Motorcycle	December	r assenger Car	Umer (Pickup/Van)	Bus	2D Single Unit	Car w/ 1 Axle Trailer	Other w/ 1 Axle Trailer	Bus	2D w/ I Axle Trailer	3 Axle Single Unit	Semi, 2S1	Car w/2 Axle Trailer	Other w/ 2 Axle Trailer	2D w/ 2 Axle Trailer	4 Axle Single Unit	Semi, 381	Semi, 2S2	Other w/ 3 Axle Trailer	2D w/3 Axle Trailer	5 Axle Single Unit	Semi, 3S2	Truck+FullTrailer (3-2)	Semi, 2S3	Semi+FullTrailer, 2S12	Semi, 3S3	Semi+Full Trailer, 3S12	7 Axle Multi's	8 Axle Multi's	9 Axle Multi's	- The state of the
}			•	\dagger	-		S		3	***	מו	9	œ	7		20	-	97	90		3							12 8	13	13 8	13 9	

Spacings in feet Weights in kips (L.bs/1000) * Suggested Axle I minimum weight threshold if allowed by WIM system's class algorithm programming

System Operating Parameters

Washington SPS-2

Validation Visit - 29 November 2006

Loop separation: From leading edge to leading edge is: 264"

Axle separation is: 120"

Leading edge of the first loop to the first axle sensor: 107" Leading edge of the first loop to the second axle sensor: 227"

Calibration factor for sensor #1:

100 kph: 120 kph: threshold: 80 kph: 6.690134 6.690134 6.690134 25

Calibration factor for sensor #2:

80 kph: 6.690134 100 kph: 6.690134 120 kph: 6.690134 threshold: 25

Dynamic: 99

TEST TRUCK PHOTOS FOR SPS WIM FIELD VALIDATION

STATE: Washington

SHRP ID: 530200

Figures

Figure 1 – Truck_1_Tractor_TO_17_53_2.83_0200.jpg	2
Figure 2 – Truck_1_Trailer_TO_17_53_2.83_0200.jpg	
Figure 3 – Truck_1_Suspension_1_TO_17_53_2.83_0200.jpg	
Figure 4 – Truck_1_Suspension_2_TO_17_53_2.83_0200.jpg	
Figure 5 – Truck_1_Suspension_3_TO_17_53_2.83_0200.jpg	
Figure 6 – Truck_2_Tractor_TO_17_53_2.83_0200.jpg	
Figure 7 – Truck_2_Trailer_TO_17_53_2.83_0200.jpg	
Figure 8 – Truck_2_Suspension_1_TO_17_53_2.83_0200.jpg	
Figure 9 – Truck_2_Suspension_2_TO_17_53_2.83_0200.jpg	
Figure 10 – Truck_2_Suspension_3_TO_17_53_2.83_0200.jpg	



Figure 1 – Truck_1_Tractor_TO_17_53_2.83_0200.jpg



Figure 2 – Truck_1_Trailer_TO_17_53_2.83_0200.jpg



Figure 3 – Truck_1_Suspension_1_TO_17_53_2.83_0200.jpg



Figure 4 – Truck_1_Suspension_2_TO_17_53_2.83_0200.jpg



Figure 5 – Truck_1_Suspension_3_TO_17_53_2.83_0200.jpg



Figure 6 – Truck_2_Tractor_TO_17_53_2.83_0200.jpg



Figure 7 - Truck_2_Trailer_TO_17_53_2.83_0200.jpg



Figure 8 – Truck_2_Suspension_1_TO_17_53_2.83_0200.jpg



Figure 9 – Truck_2_Suspension_2_TO_17_53_2.83_0200.jpg



Figure 10 - Truck_2_Suspension_3_TO_17_53_2.83_0200.jpg